

Model-driven Self-Optimization

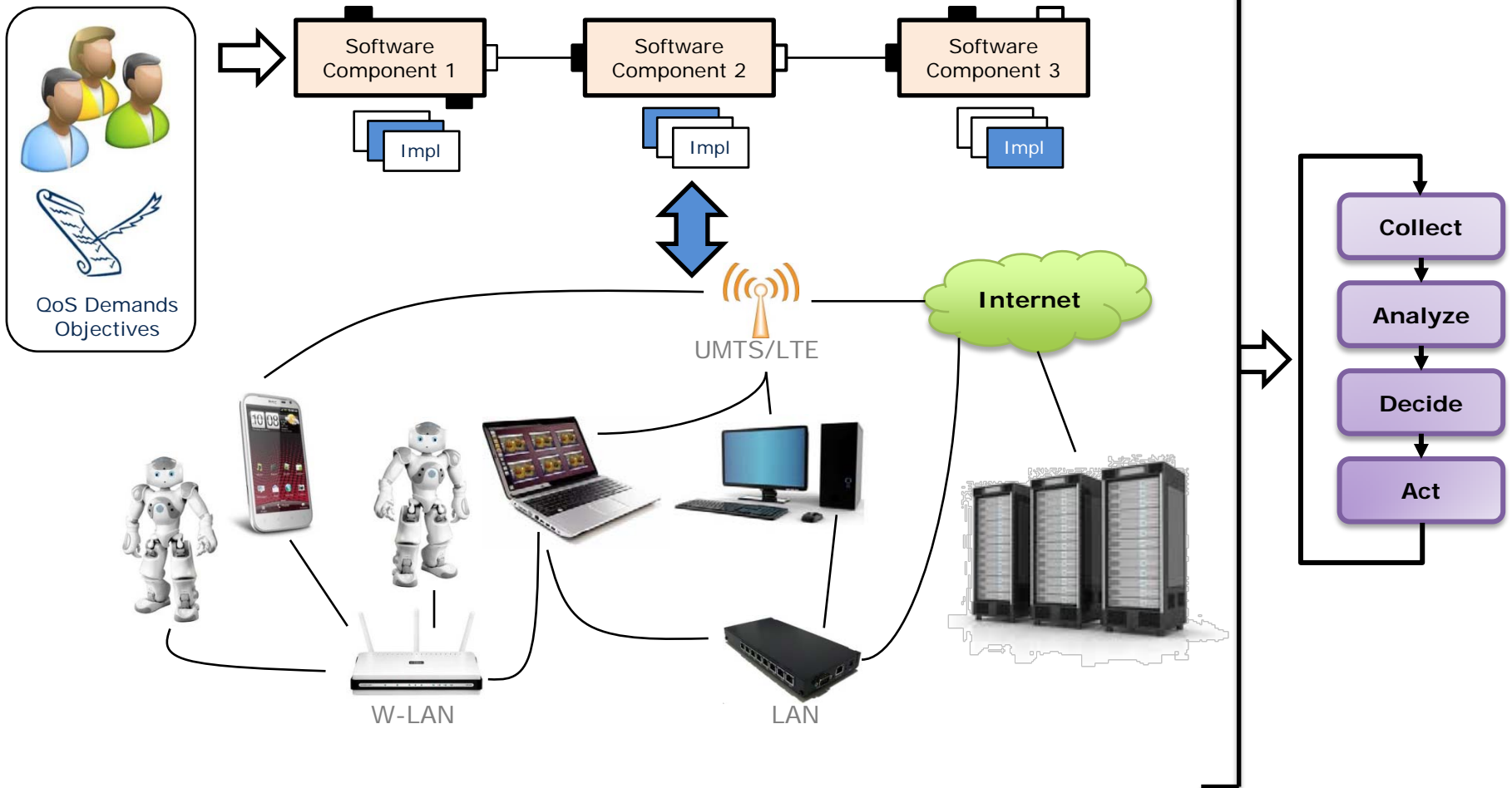
by Integer Linear Programming and Pseudo-Boolean Optimization

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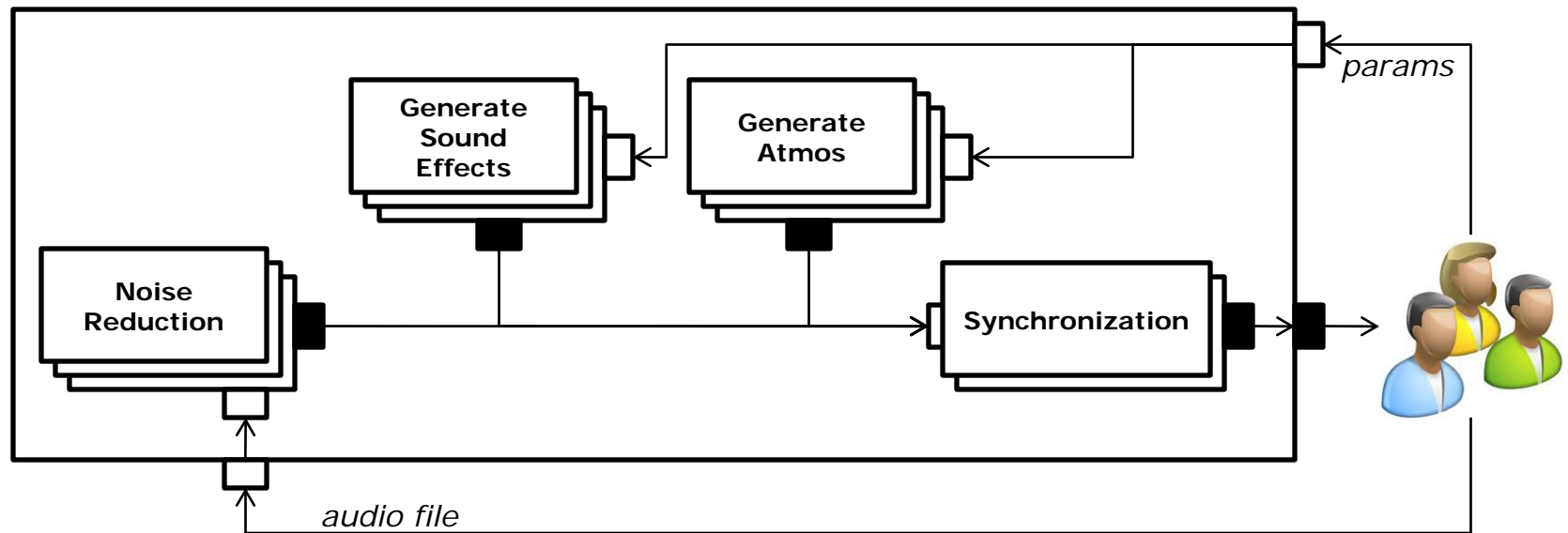


Self-optimizing distributed hardware/software systems

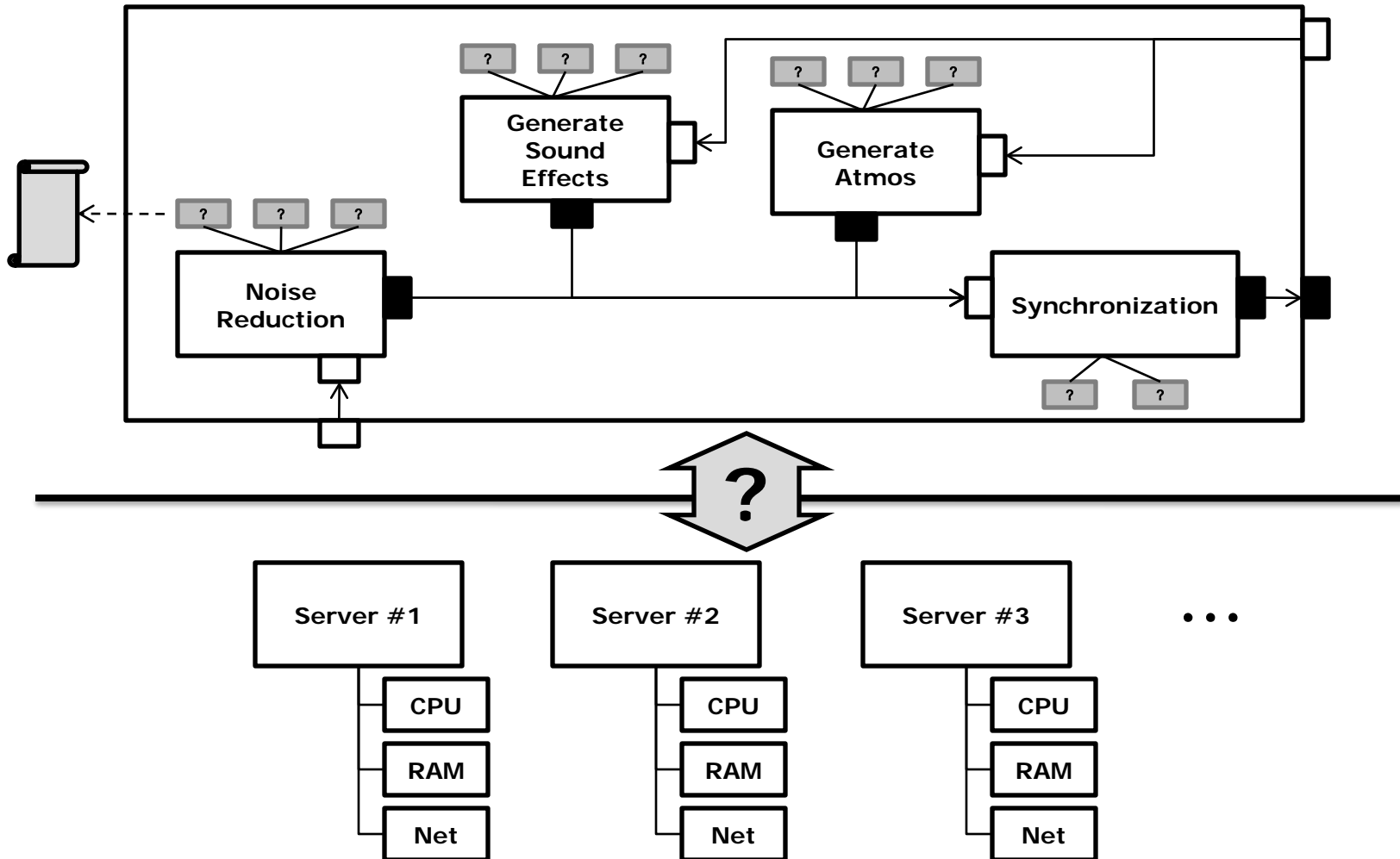


Example: Audio-Processing (<https://auphonic.com/>)

- Customers send audio files for grafting
 - Noise reduction
 - Sound design (e.g., adding synthesized sounds)
 - Synchronization of multiple audio streams
 - Etc.



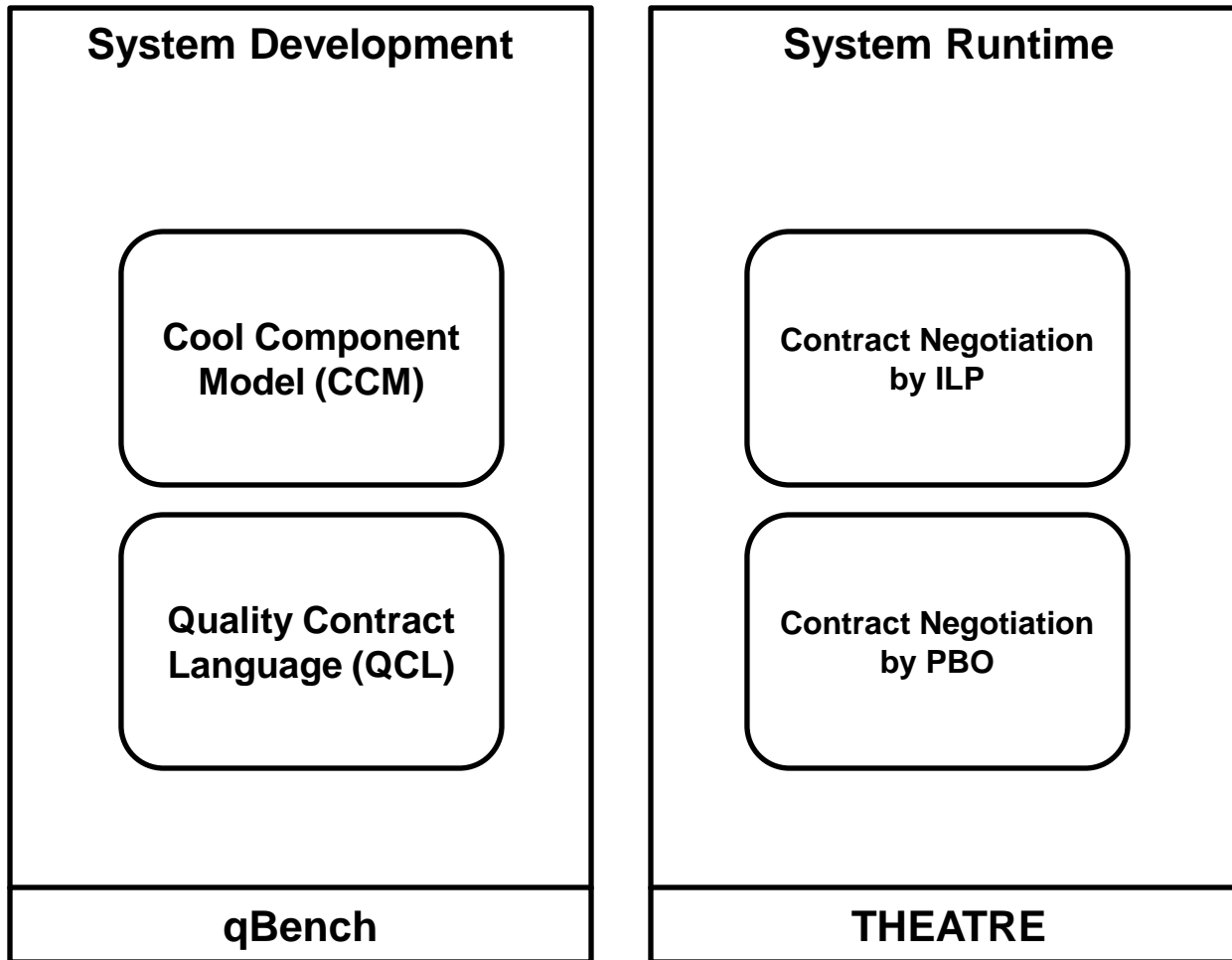
- **Problem #1:** Formulation of optimization problem
 - Developers **reinvent solutions** to almost equal problems
 - NFPs of interest change
 - Resources of interest change
 - But, the general optimization problem remains the same

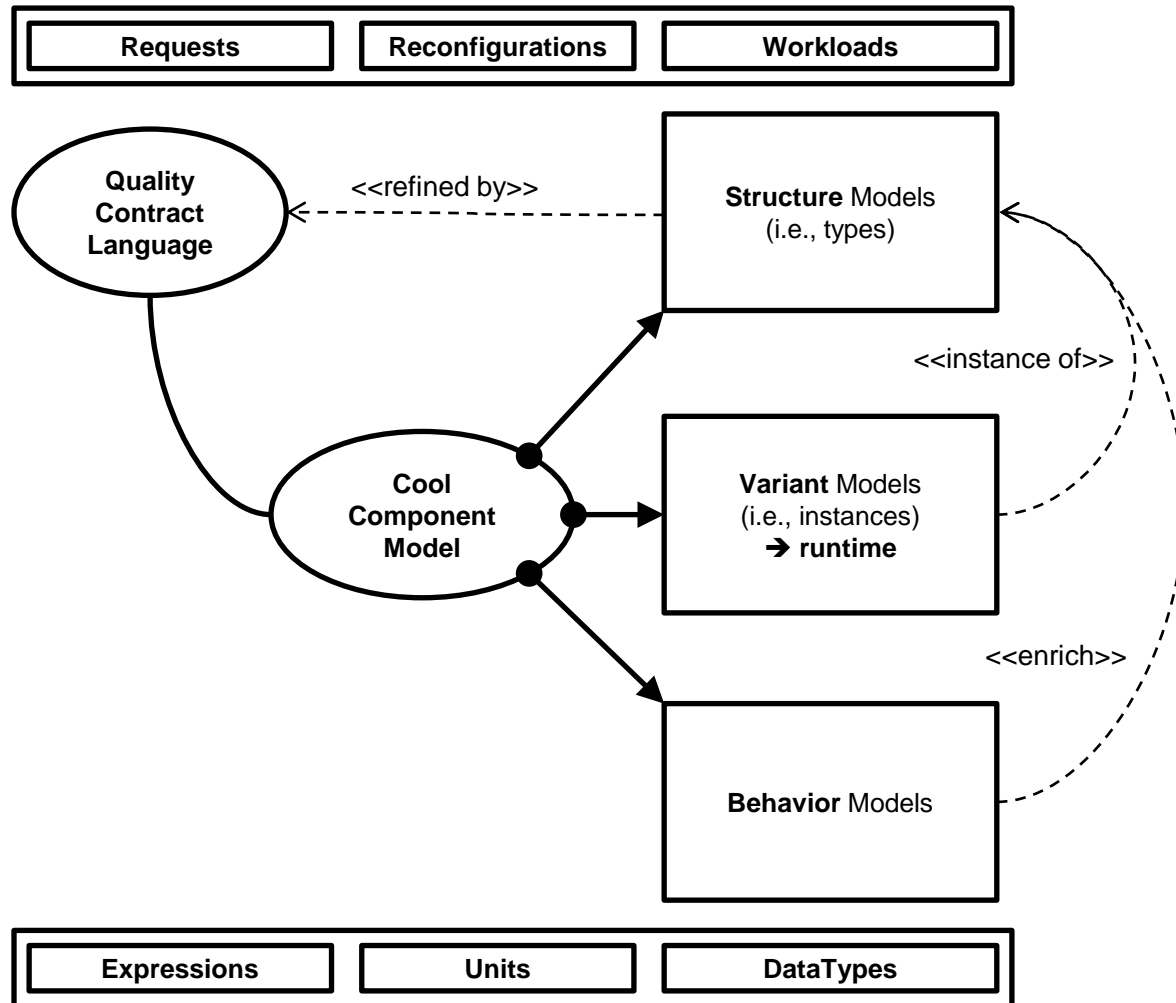


- **Problem #1:** Formulation of optimization problem
 - Developers **reinvent solutions** to almost equal problems
 - NFPs of interest change
 - Resources of interest change
 - But, the general optimization problem remains the same
- **Solution:**
 - Model-driven development of the system
 - Use runtime and design-time models of the system to **generate the optimization problem**

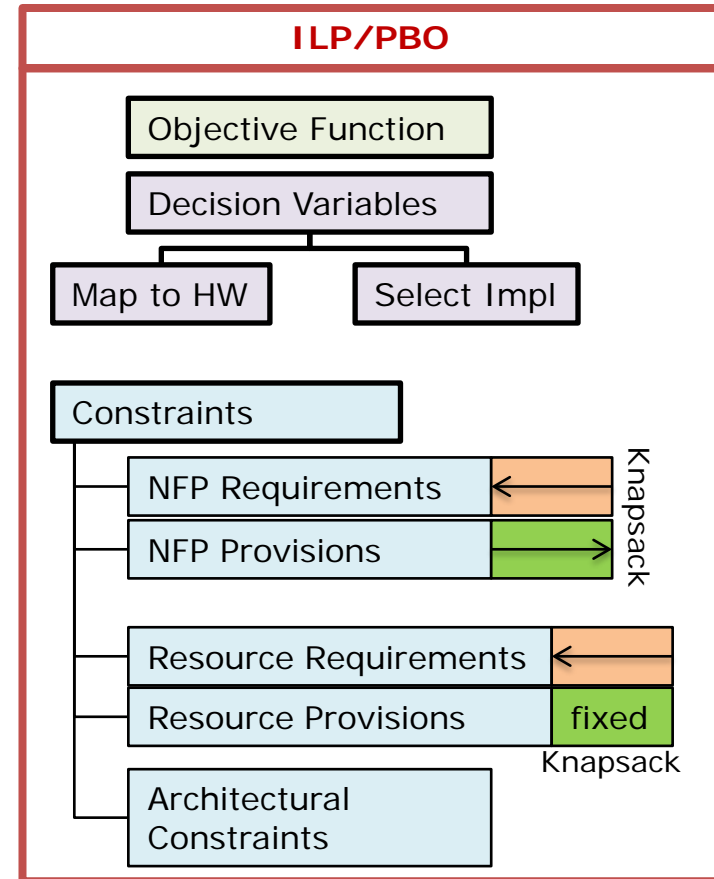
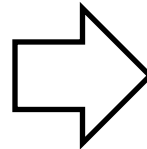
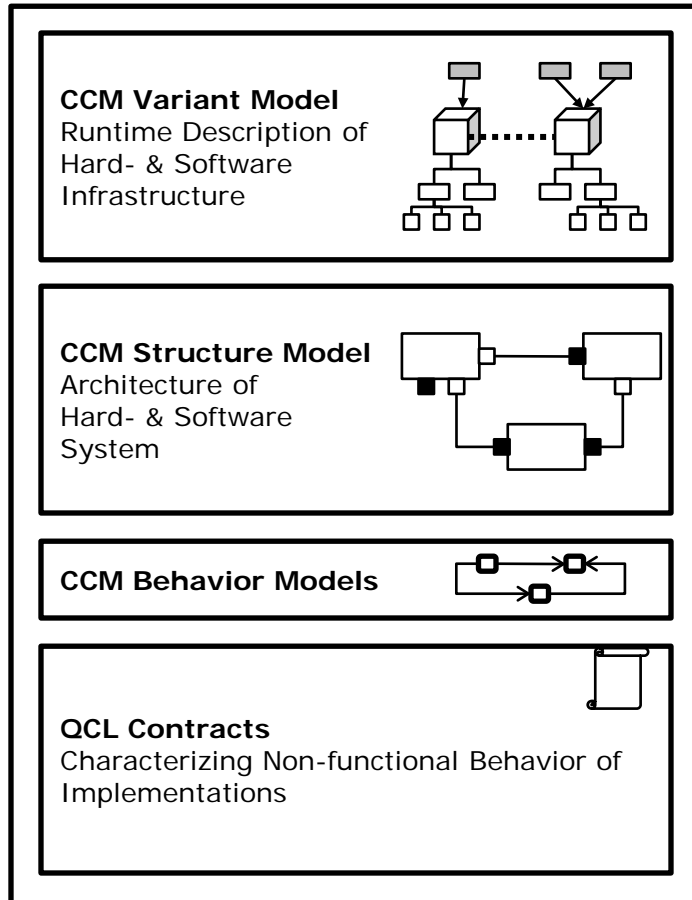
- **Problem #2:** Complex dependencies between NFPs have to be considered
 - Optimization problem relies on these dependencies (e.g., trade-off between response time and noise level)
 - **Solution:**
 - **QoS contracts** covering the non-functional behavior of implementations

- **Problem #3:** High computational complexity of optimization
 - Can optimization be performed in budget?
 - **Solution:**
 - **Scalability analysis** of the approach



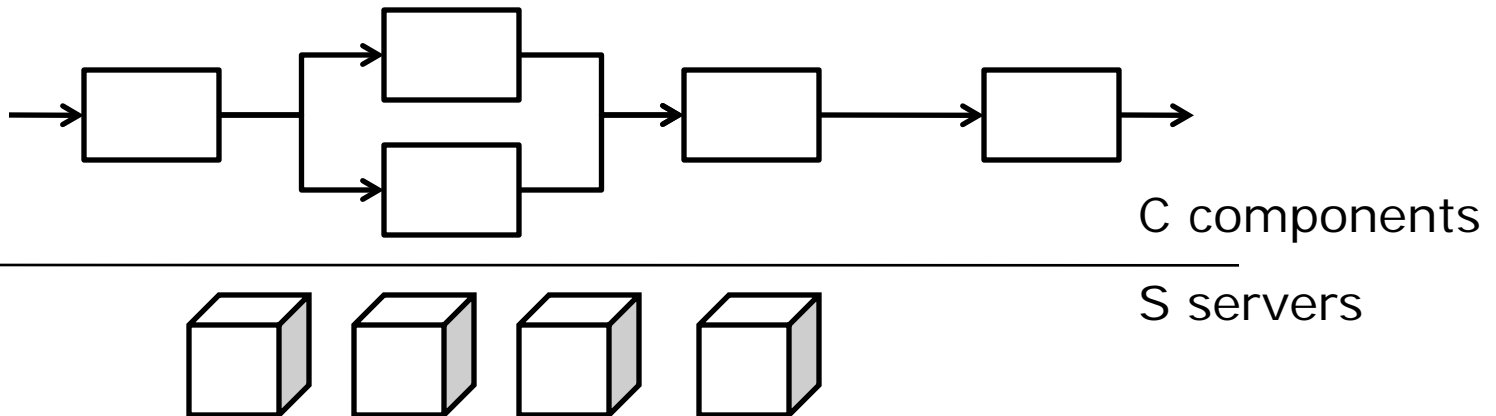


```
1 contract VLC implements VideoPlayer.play {
2
3   mode fluent {
4     requires component Decoder {
5       min dataRate: 9 MB/s
6     }
7     requires resource Net {
8       min bandwidth: 10 MB/s
9     }
10
11    provides min frameRate: 25 FPS
12  }
13  mode lowQuality {
14    /* More requirements and provisions here ... */
15  }
16 }
```

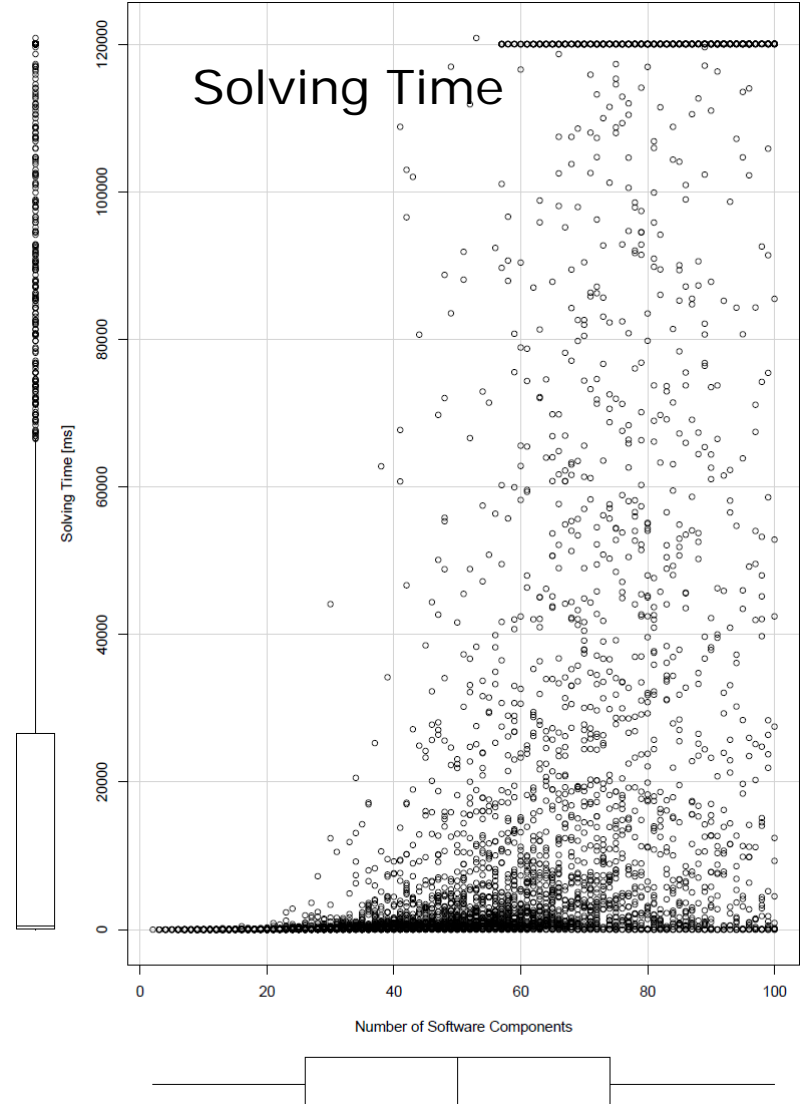
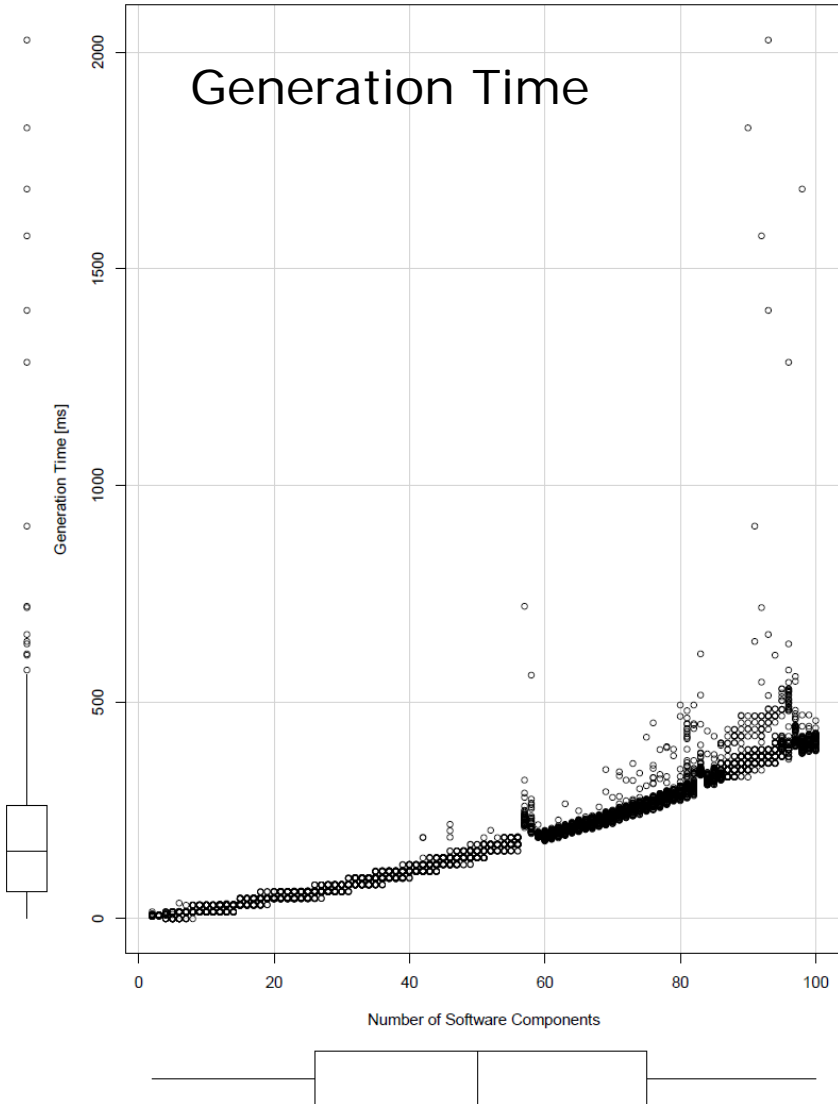


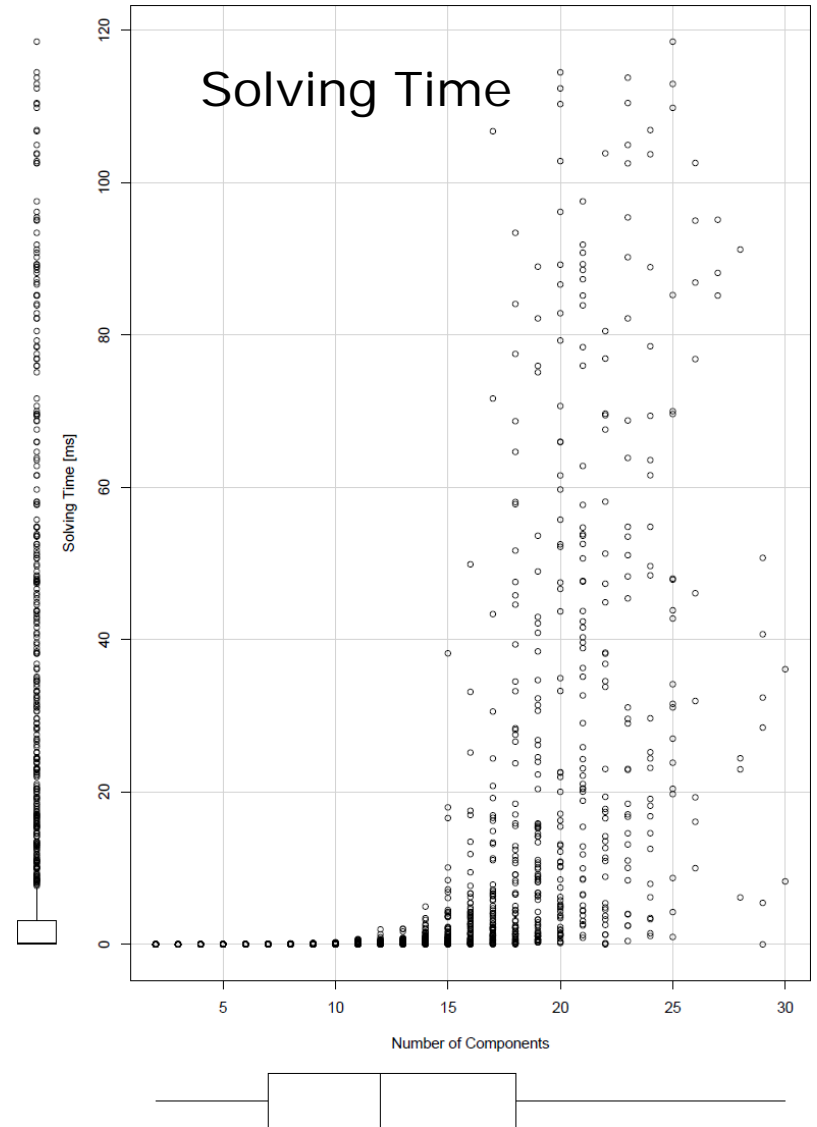
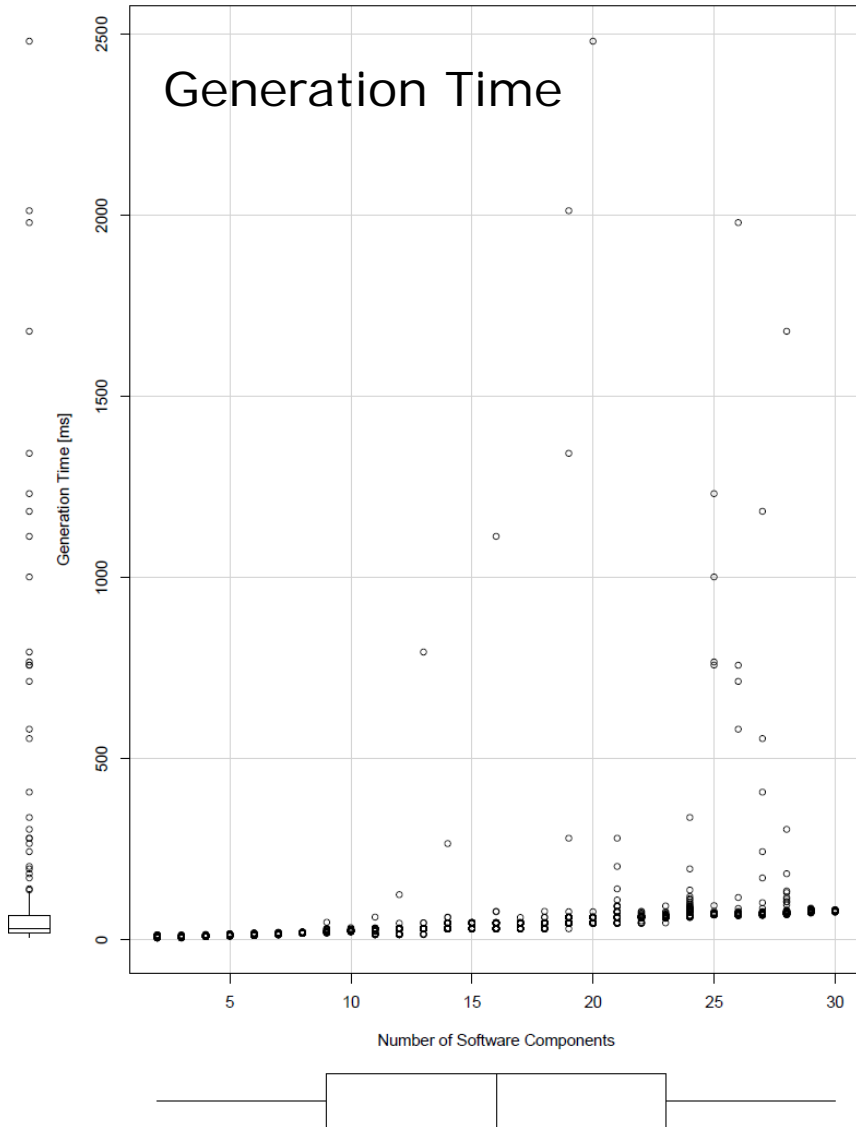
- Pseudo-Boolean Optimization (PBO) = 0-1 Integer Linear Programming (ILP)
 - i.e., only boolean decision variables
- Allows for application of SAT-solving (e.g., DPLL)
- Could be faster than general ILP solving

- Performed on typical class of systems: **pipe-and-filter style**



- Each component type has 2 implementations
 - 2 NFPs per implementation
-
- Measurements taken for $C \times S$ systems from **$C = [2..100]$ and $S = [2..100]$**





- **Problem #1:** Developer's reinvent solutions to optimization problems
 - Application of **runtime models** to **generate** the optimization problem
- **Problem #2:** Complex dependencies between NFPs have to be considered
 - Application of **QoS contracts** covering non-functional behavior of implementations
- **Problem #3:** High computational complexity of optimization techniques
 - **Scalability Analysis**
 - ILP solving is predictable up to 25 component types
 - **ILP solving is feasible up to 100 component types**, if typical processing time is »30s
 - **ILP performs much better than PBO**
 - PBO solving is feasible up to 20 component types
 - PBO solving is predictable up to 10 component types

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