



# Software Composition – Some Challenges of the Next Decade

## **Software Composition 2012**

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Technische Universität Dresden  
Chair of Software Engineering

Prague, June 1, 2012

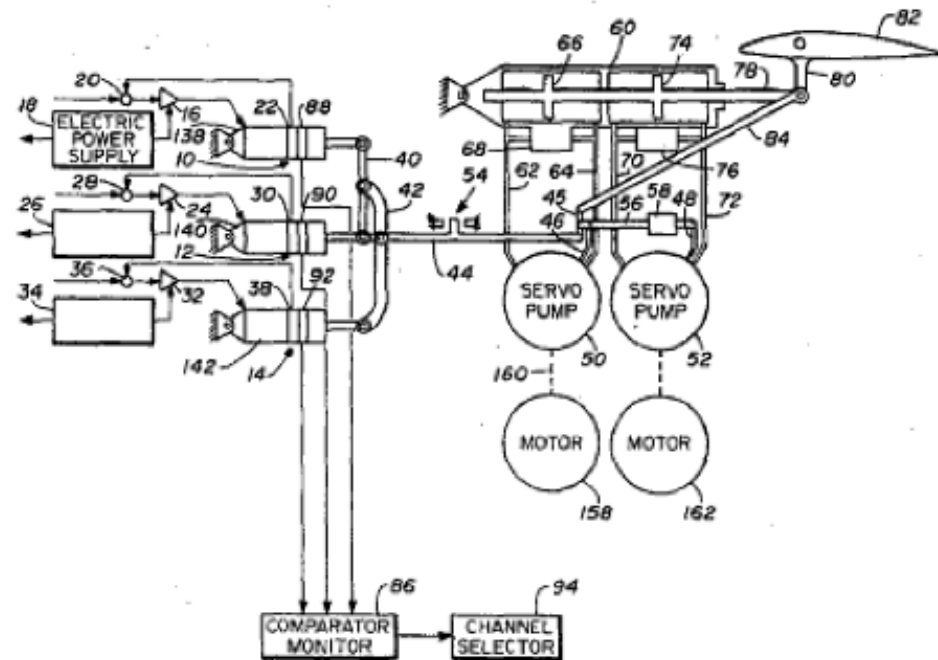
- Software composition has come a long way from the times of the end of the 80s, when the problem of inheritance anomaly stopped the parallel object-oriented languages. It is time to look back at some of the old challenges that started the field and discuss, how we can solve them now or in the near future, the next decade. These challenges include
  - the coordination of parallel objects in pools
  - context specifications based on concerns and roles,
  - and the quality-based dispatch in multi-objective optimized systems (MOO systems) for the modeling and programming of cyber-physical systems (life-by-wire).
- The talk gives an overview on these challenges for software composition for the next decade, and formulates several research problems (The Prague composition manifesto).

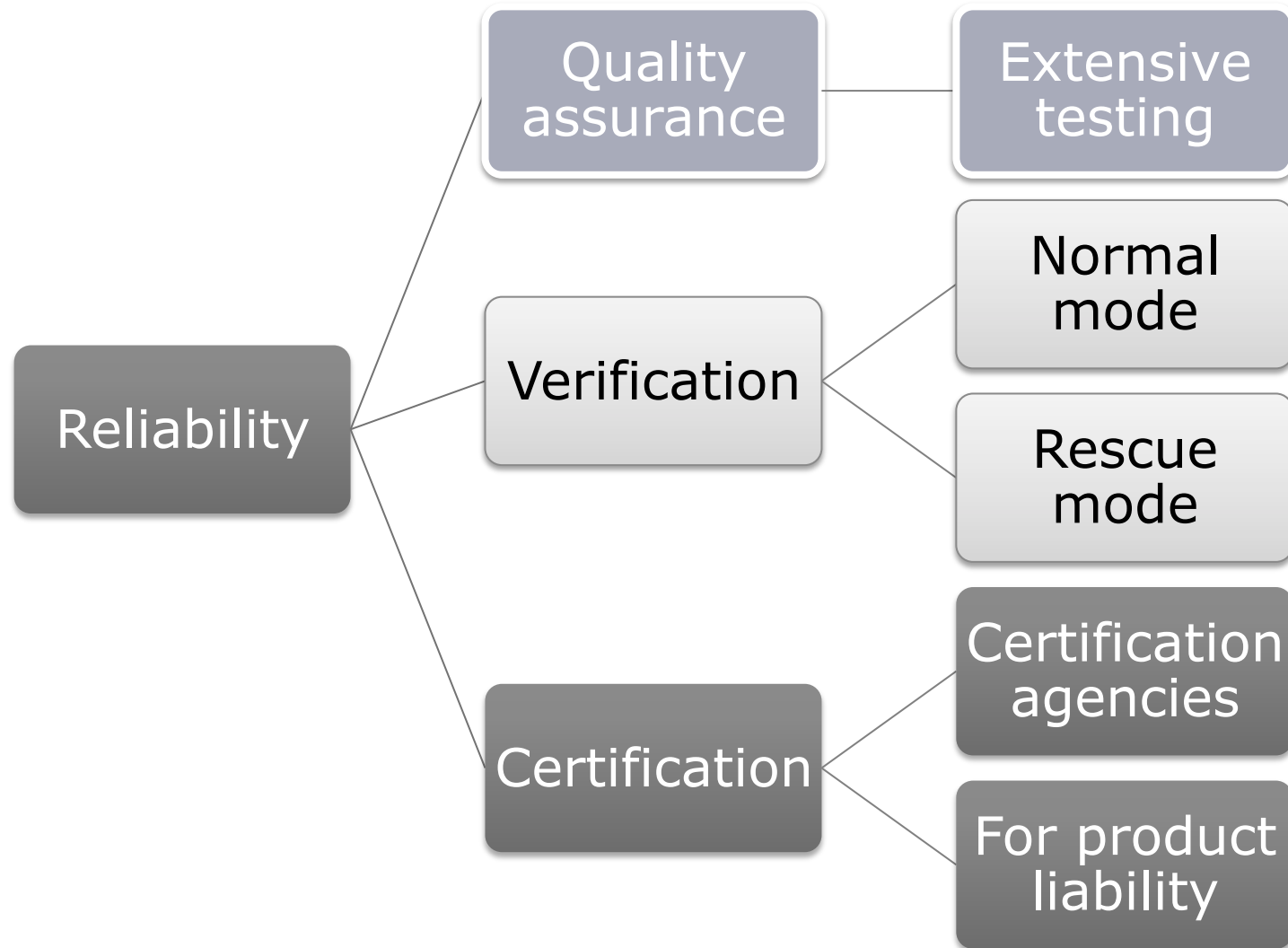
1. Life-by-Wire
2. Separations of Concerns and composition
3. Parallelism: the POOL problem revisited
4. Context-sensitivity: Reliable adaptivity with quality roles
5. Efficiency-based development with MOO architectures
6. The ultimate challenge: Specifying composition systems
7. The Prague composition manifesto

With cyber-physical systems (CPS)

## **CHAP.1 LIFE-BY-WIRE**

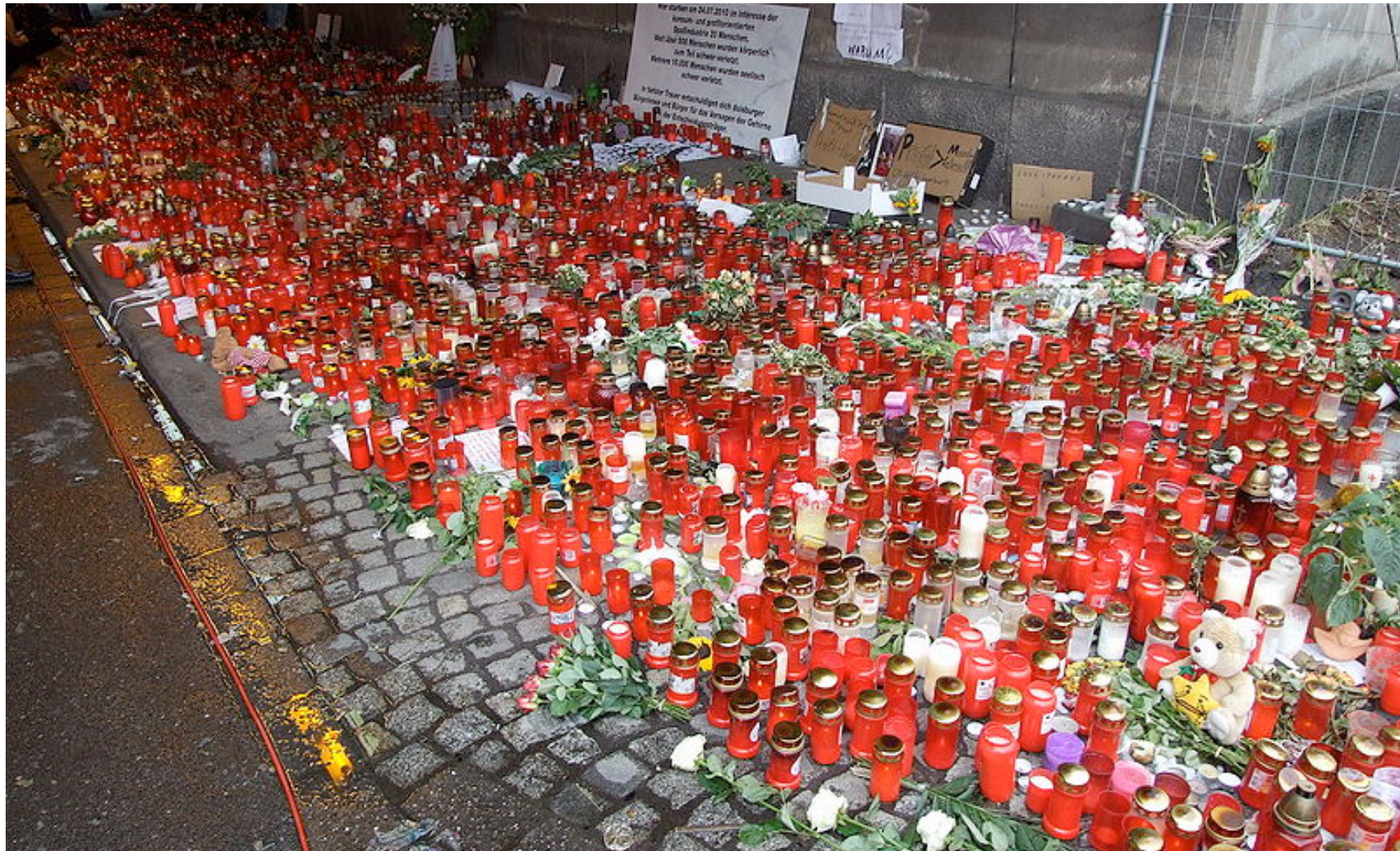
- **FLY-BY-WIRE**
- William G. Redmond - US Patent 3,679,156, 1972
- <http://www.google.com/patents?hl=de&lr=&vid=USPAT3679156&id=GTswAAAAEBAJ&oi=fnd&dq=fly-by-wire&printsec=abstract#v=onepage&q=fly-by-wire&f=false>





# CHAP.1.2 THE NEAR FUTURE: HELP-BY-WIRE





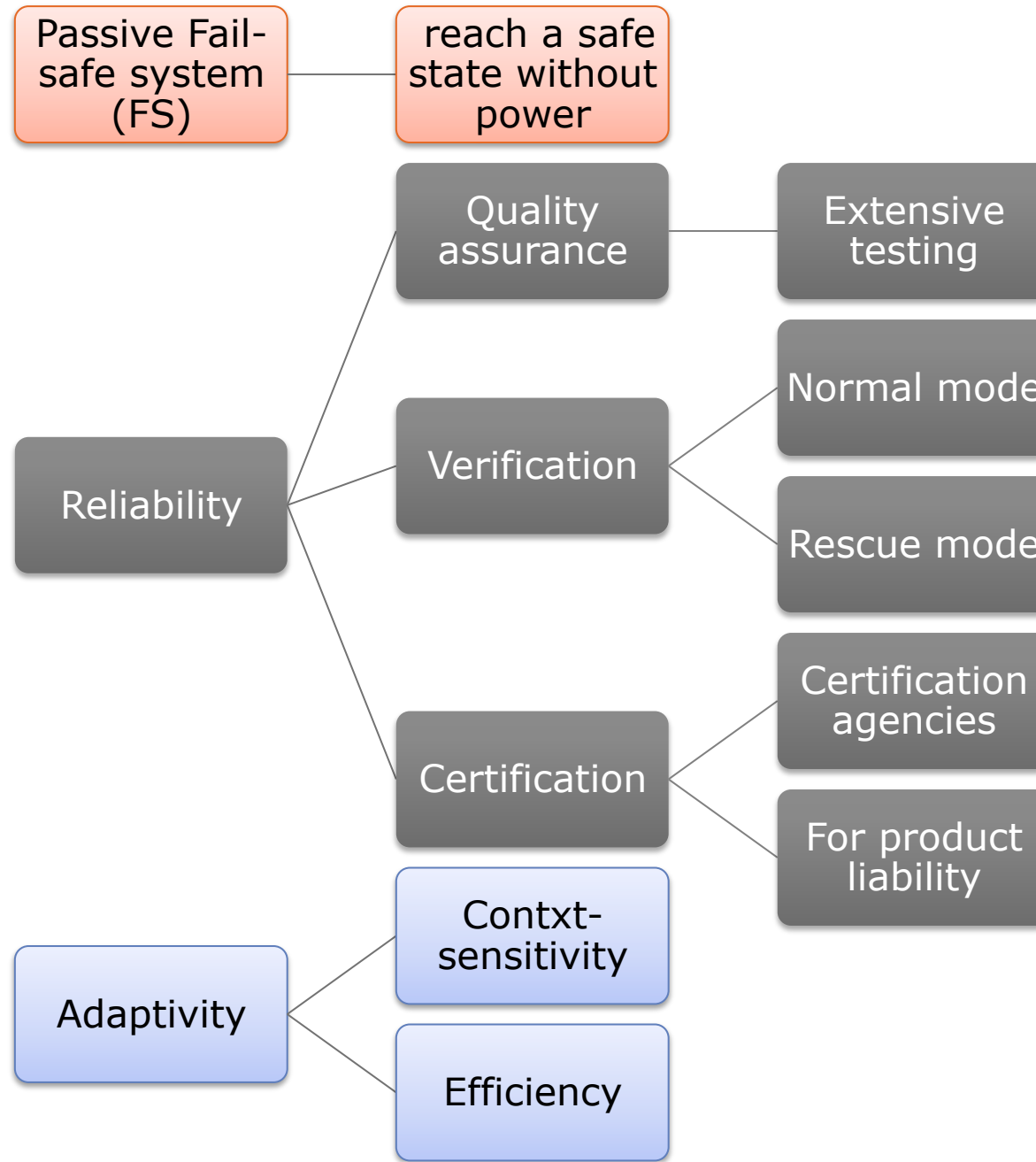


- „In der Europäischen Union werden jährlich ueber 7.000 Fussgänger und 2.000 Fahrradfahrer bei Verkehrsunfällen getötet. Hunderttausende werden darüber hinaus bei Verkehrsunfällen verletzt.“
- [M. Bischoff. Aktive Sicherheitssysteme fuer den Schutz von Fussgaengern im Strassenverkehr]

Um 4.30 Uhr hatte sich Regina F. auf den Weg zur Arbeit gemacht. Von der Britzer Straße in Schöneweide zum Putzen nach Marienfelde. Sie schaffte es nicht mal bis zum S-Bahnhof.

Viel zu schnell kam ein Kombi um die Ecke gefahren. So schnell, dass das Auto aus der Kurve flog und über den Bürgersteig raste. Durch den Aufprall wurde Regina F. auf die Straße geschleudert. Nur kurz hielt der Mann an, dann gab er Gas und raste davon.





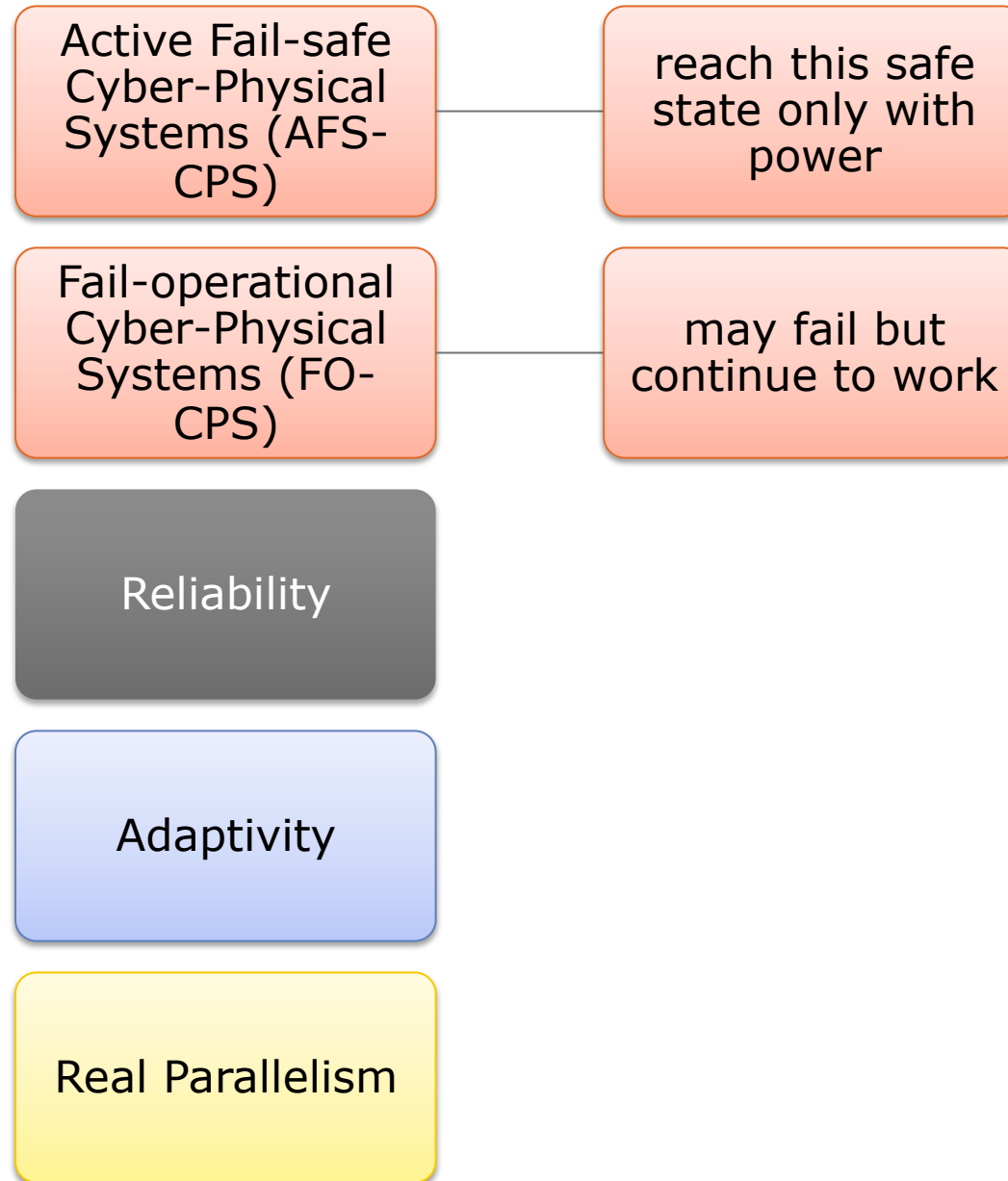
## 1.3 THE MID-TERM FUTURE: MOVE-BY-WIRE





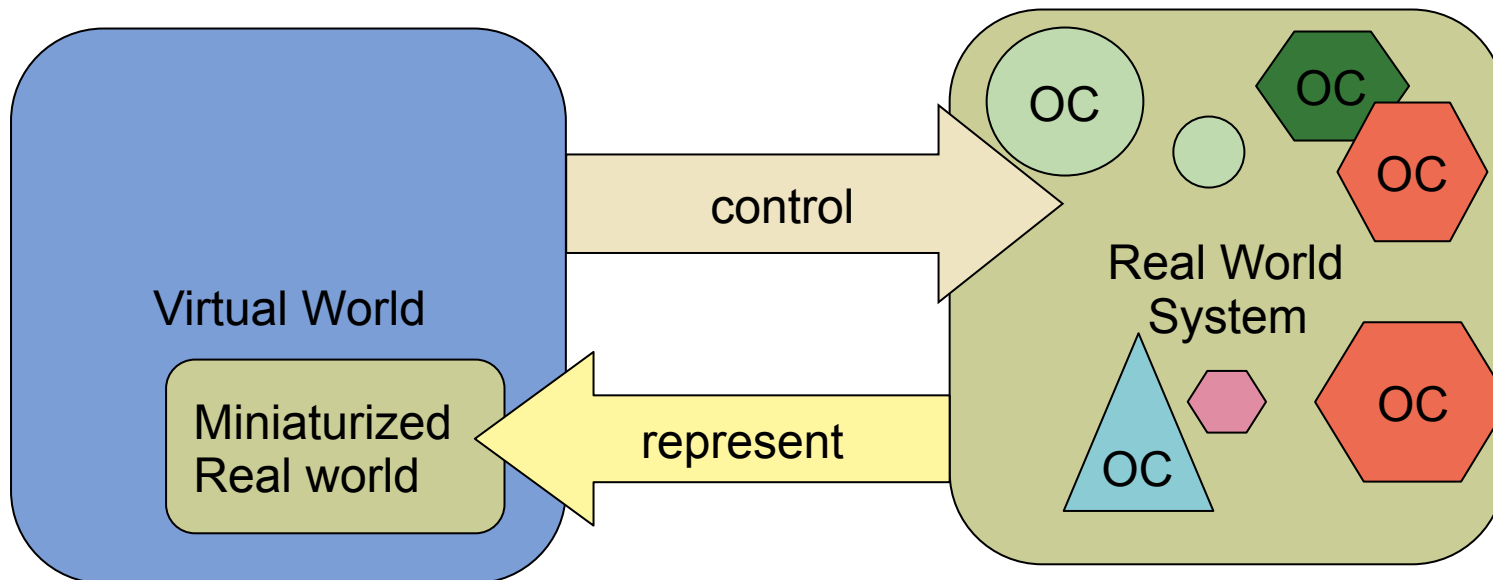


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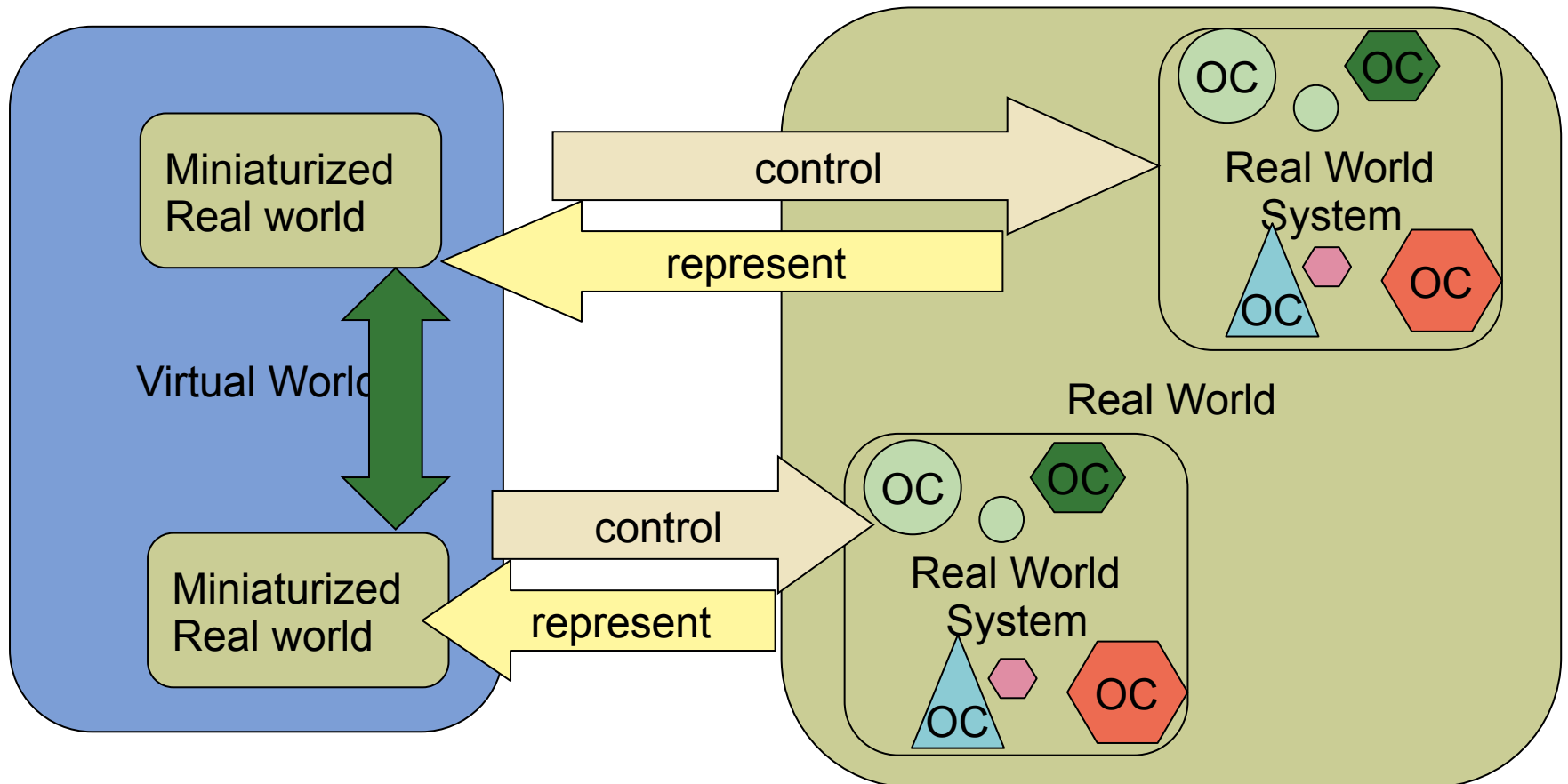


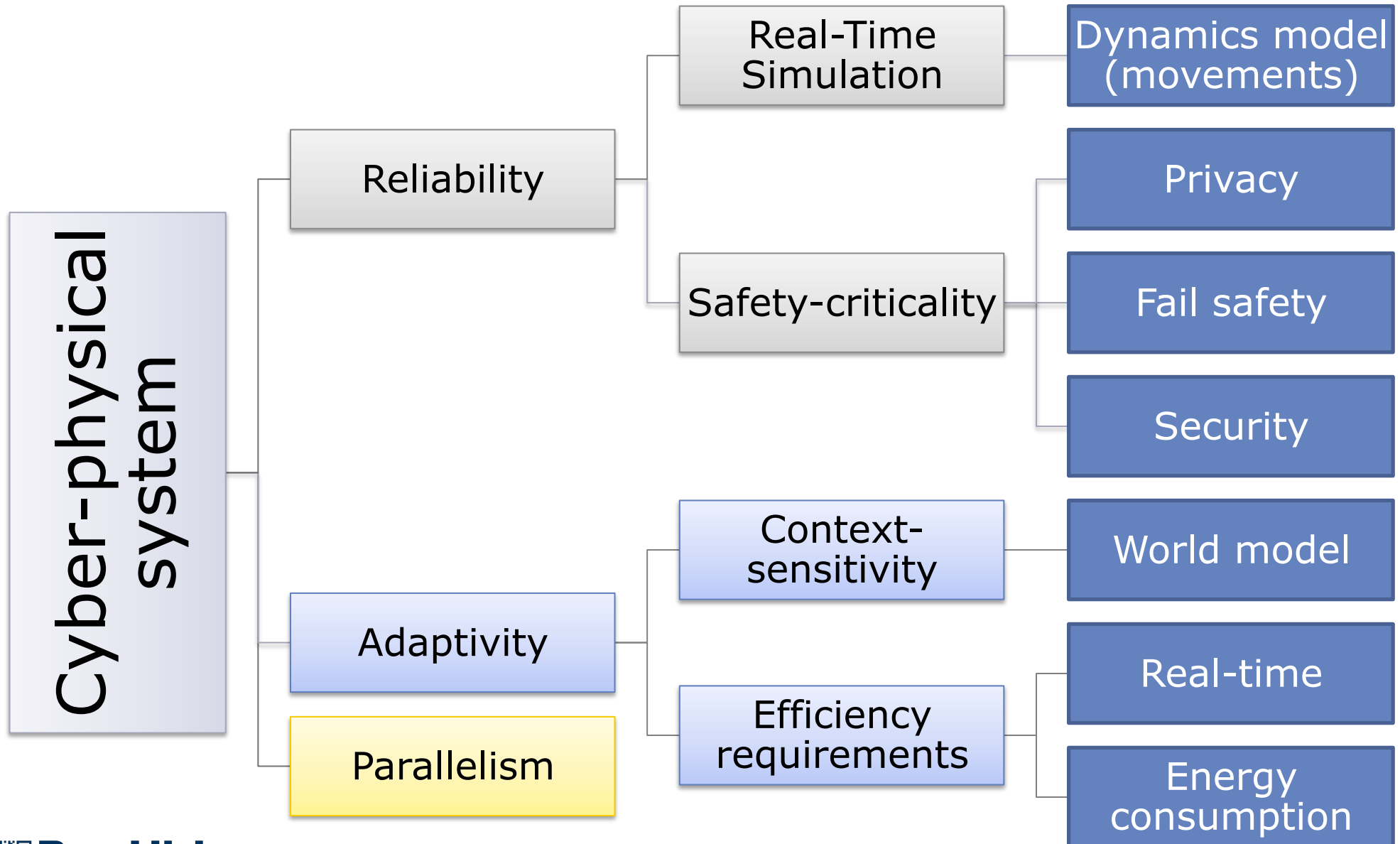


- Control of the intelligent things in space and time
  - Self regulation
  - Self optimization
  - Self organisation
- Dual reality



- Systems of CPS





# 2. SEPARATION OF CONCERNS AND COMPOSITION

- E.W.Dijkstra in EWD 447 „On the role of scientific thought“:
- Let me try to explain to you, what to my taste is characteristic for all intelligent thinking. It is, that one is willing to study in depth an aspect of one's subject matter in isolation for the sake of its own consistency, all the time knowing that one is occupying oneself only with one of the aspects.
- It is what I sometimes have called "*the separation of concerns*", which, even if not perfectly possible, is yet the only available technique for effective ordering of one's thoughts, that I know of. This is what I mean by "focussing one's attention upon some aspect".

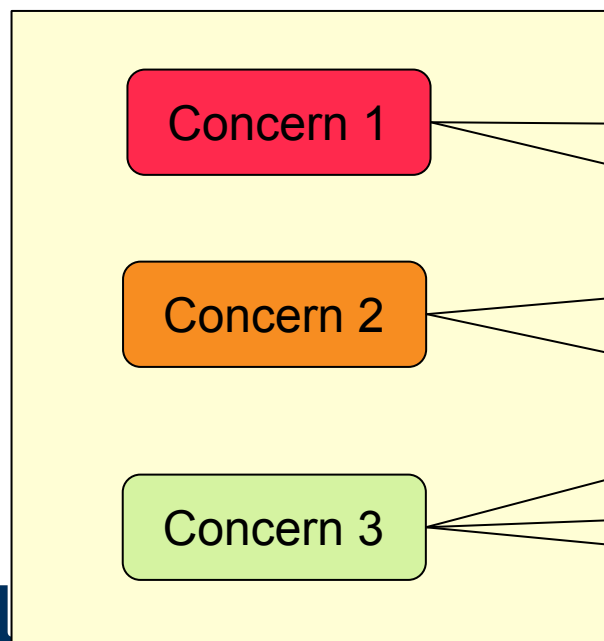
- The current approaches to aspect-orientation are not covering this:
  - SoC must support decomposition **and** composition
  - Changing focus is not supported
  
- **Ch 1: How can we conceptualize separations of concerns so that decomposition and composition are supported?**



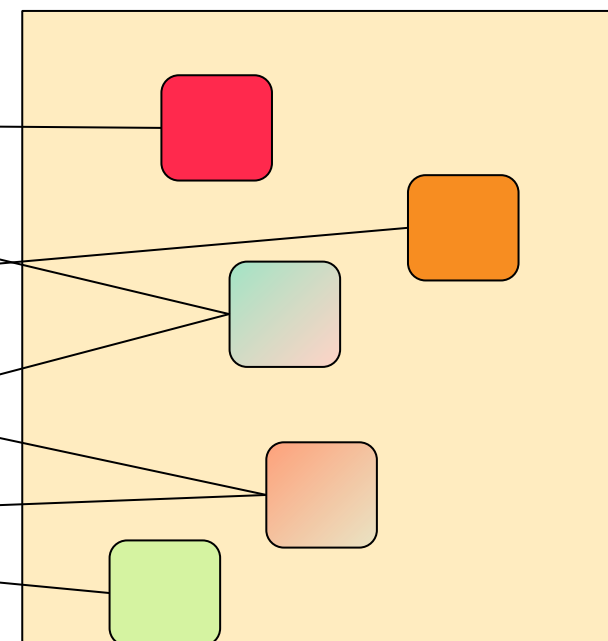
A **view** is a representation of a whole system from the perspective of a related set of concerns [ISO/IEC 42010:2007, Systems and Software Engineering -- Recommended practice for architectural description of software-intensive systems]

- ▶ An **artefact space** (solution space) consists of a set of components, models, or programs
- ▶ An **concern (aspect)** is *related* to a **slice** of the components of the artefact space, the **view**
- ▶ A **concern space** consists of a set of concerns and an algebraic structure

Concern space



Artefact space



# Ex.: A Flat Concern Space: Color Coding of Concerns

```

AspectJ
File About
Aspect Name: color
0000 public void init() {
0001     super.init();
0002     setPort(getBaseLayer().getPort());
0003     setPort(8080);
0004     public void run() {
0005         while(true) {
0006             public void waitFor();
0007             public void waitFor();
0008             public void waitFor();
0009             public void run() {
0010                 setPort(getBaseLayer().getPort());
0011                 s = new Socket(getHost(), getPort());
0012                 die = new DataInputStream(s.getInputStream());
0013                 pr = new PrintWriter(s.getOutputStream());
0014                 input = die.readLine();
0015             }
0016             public void stop() {
0017                 ps.println("bye");
0018                 die.close();
0019                 pr.close();
0020                 s.close();
0021             }
0022             public void paint(Graphics g) {
0023             }
0024             public boolean mouseDown(Event evt, int x, int y) {
0025                 ps.println("key: " + evt.getKeyCode());
0026                 ps.println(" ");
0027             }
0028             public void keyPressed(int key, int x, int y) {
0029             }
0030             public boolean handleEvent(Event evt) {
0031             }
    }
    
```

```

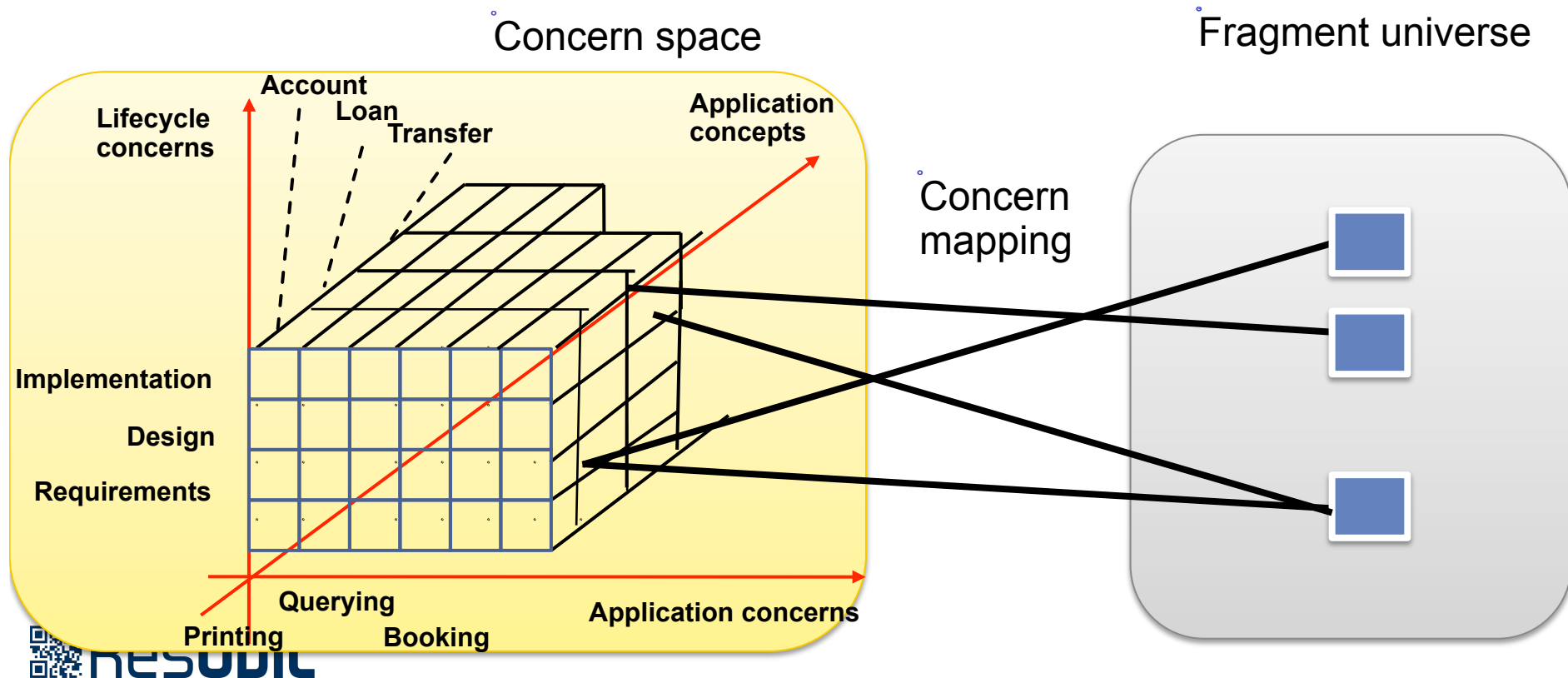
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```

```

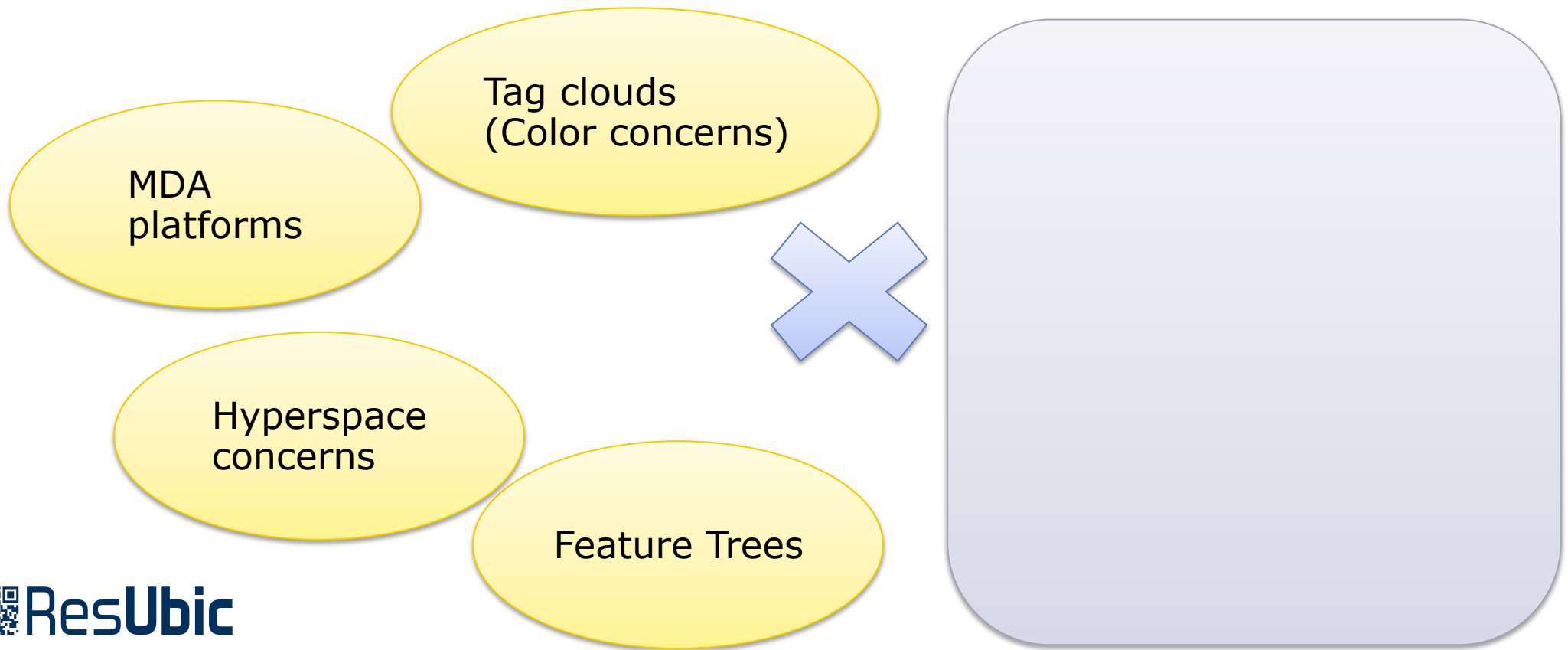
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```

Fragments can be colored with regard to a certain concern (concern mapping)  
[Panas, Andersson, Aßmann: The Editing Aspect of Aspects SEA 2002]

- ▶ Concern space and fragment universe connected via a concern mapping (crosscut graph)
- ▶ One fragment can relate to many concerns:
  - (concern\_1, .., concern\_n) x fragment
- ▶ The concern mapping results from selection/query expressions

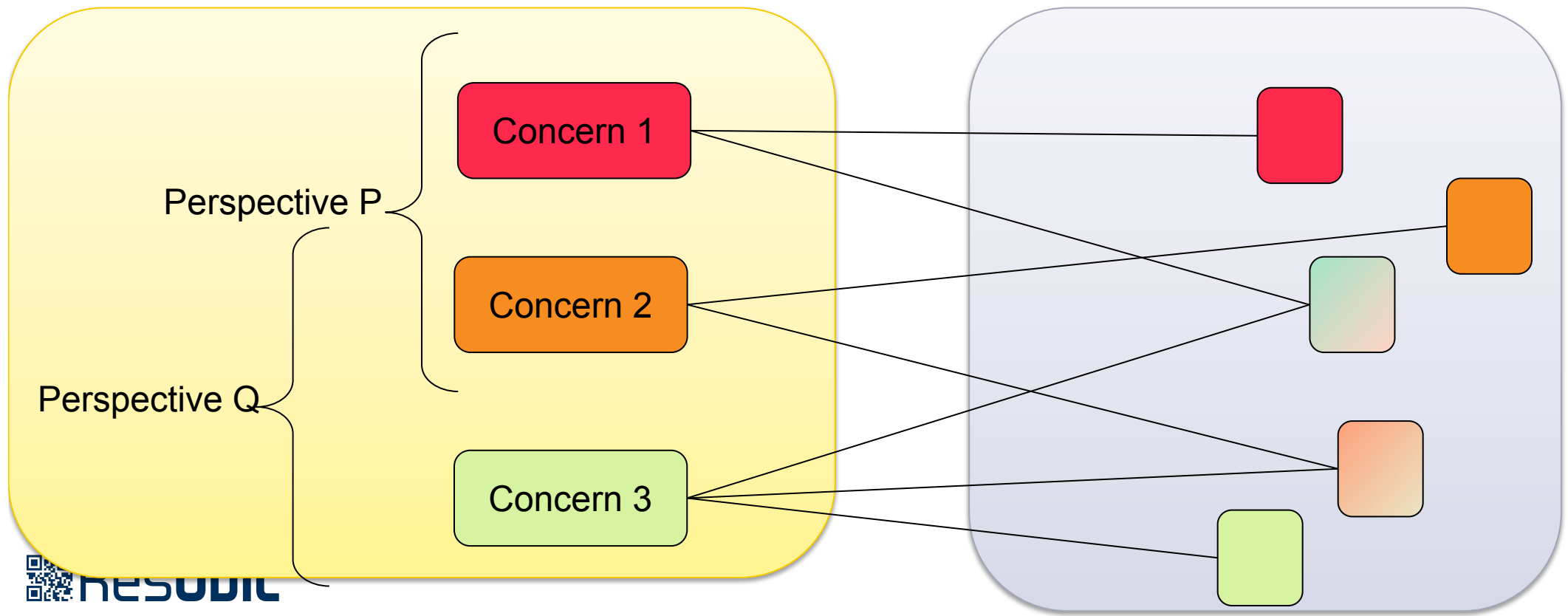


- ▶ A **perspective (viewpoint)** consists of a set of concerns in the concern space, with algebraic structure
- ▶ A **perspective model** contains a set of perspectives
- ▶ Refined: A **concern space** contains a set of perspectives and concerns *with algebraic structure*



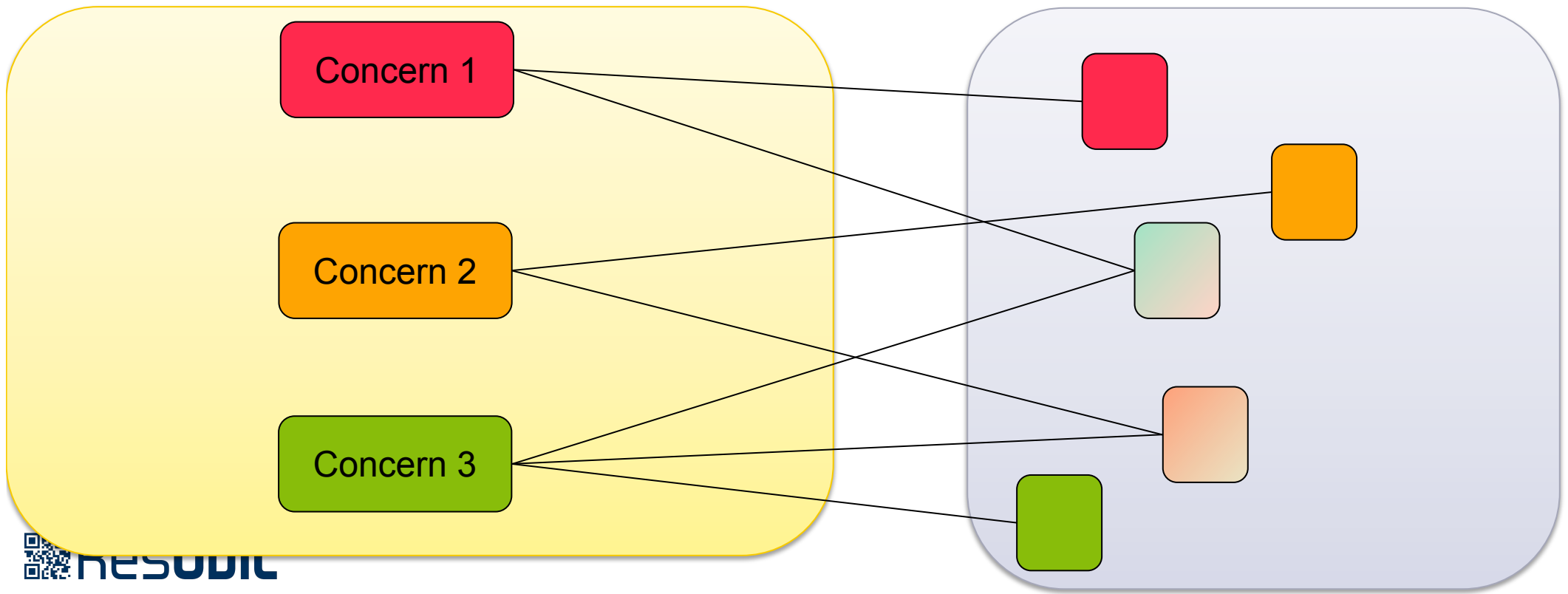
- ▶ Perspective models induce systematic aspect-oriented decompositions
  - Hyperspaces
  - Kruchten 4+1 views of software architecture
  - RM-ODP
  - Zachmann framework
- ▶ Architectural Decomposition
  - Architecture
  - Application
- ▶ Platform-oriented Decomposition in MDA
  - Essential activities in the PIM
  - Platform 1
  - .. Plattform n

- ▶ A **SoC Space** is a triple  $(C, M, A)$  with
  - Concern space  $C$
  - Concern mapping  $M$
  - Artefact space  $A$
- Concerns select views for focussing; interpretation by composition

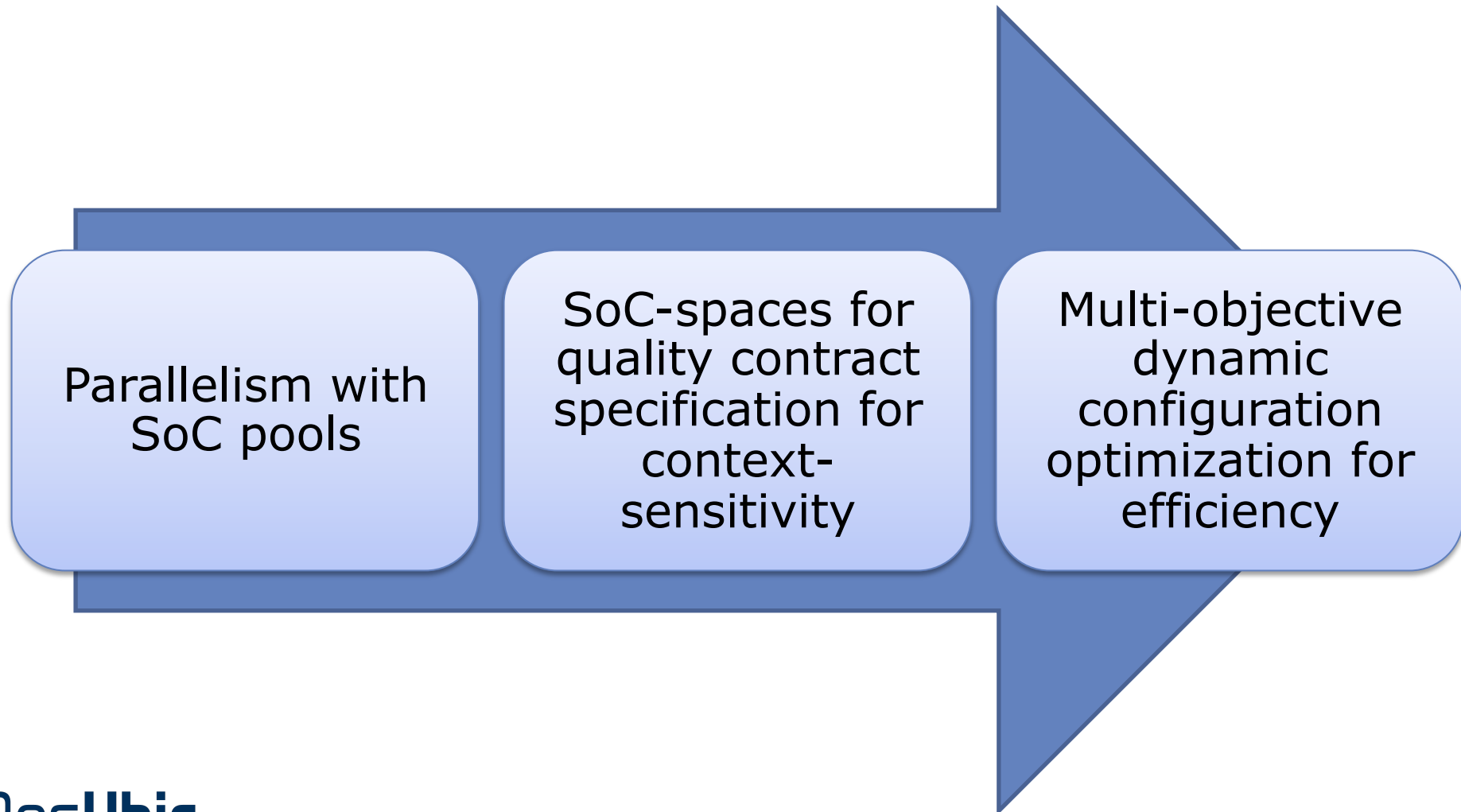




- ▶ SoC-space für modules:
  - For all modules: color with a concern
- ▶ SoC-space for components:
  - For all components: color with a concern
- ▶ SoC-space for arbitrary fragments, such as activities, stores, places
  - For all model elements: color with a concern



- **Ch 1.2: How can we metamodel SoC spaces so that they support composition and decomposition?**



- For CPS, we need Parallel OO Languages

# 3) PARALLELISM: THE POOL PROBLEM REVISITED

Let me try to explain to you, what to my taste is characteristic for all intelligent thinking.

It is, that one is willing to study in depth an aspect of one's subject matter in **isolation** for the sake of its own **consistency**, all the time knowing that one is occupying oneself only with one of the aspects.

It is what I sometimes have called "the separation of concerns" ..

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**Parallelism** results from the fact that all threads can focus on the data of their concern.

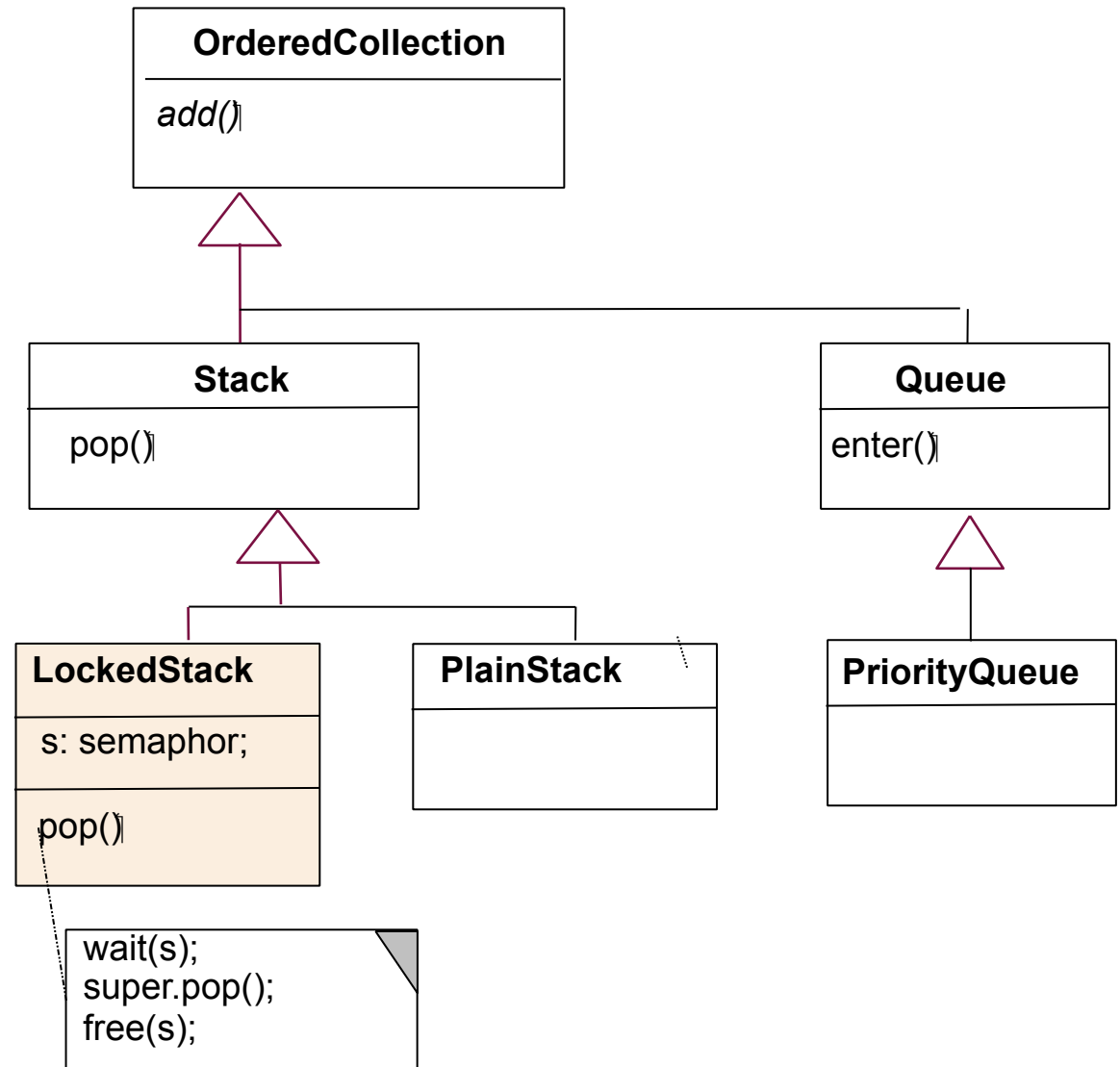
1980s: Parallel object-oriented languages (POOL)

**1991: Inheritance Anomaly**

1988: Composition Technology (Aksit)  
1994: Generic Synchronization Policies (McHale)  
1988-94: Composition Filters (Aksit)

1996: Aspect-oriented Programming (AOP)  
1996: D+RIDL (Lopes), 1999: Aspect/J (Kiczales)  
2003: Transaction MDA (Löcher)

- In a parallel program or library, where should synchronization code be inserted?
  - Stack?
  - Queue?
  - OrderedCollection?
  - Collection?
  - Object?



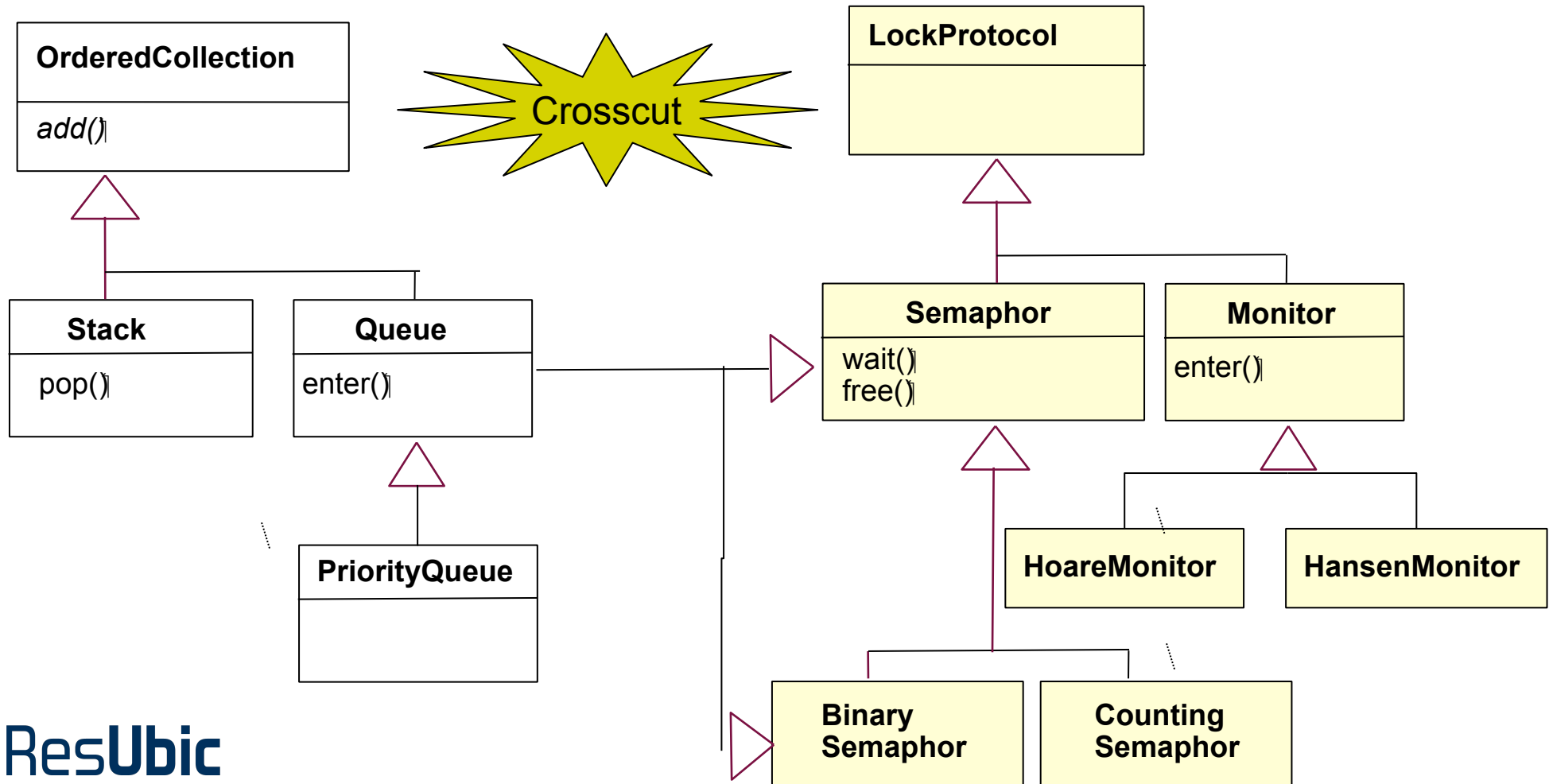
- At the beginning of the 90s, parallel object-oriented languages failed, due to the inheritance anomaly problem

**Inheritance anomaly:** In inheritance hierarchies, synchronization code is intermingled with the algorithm and cannot be easily exchanged

**Synchronization tangling:** Because synchronization code *braces* code, it is *tangling*

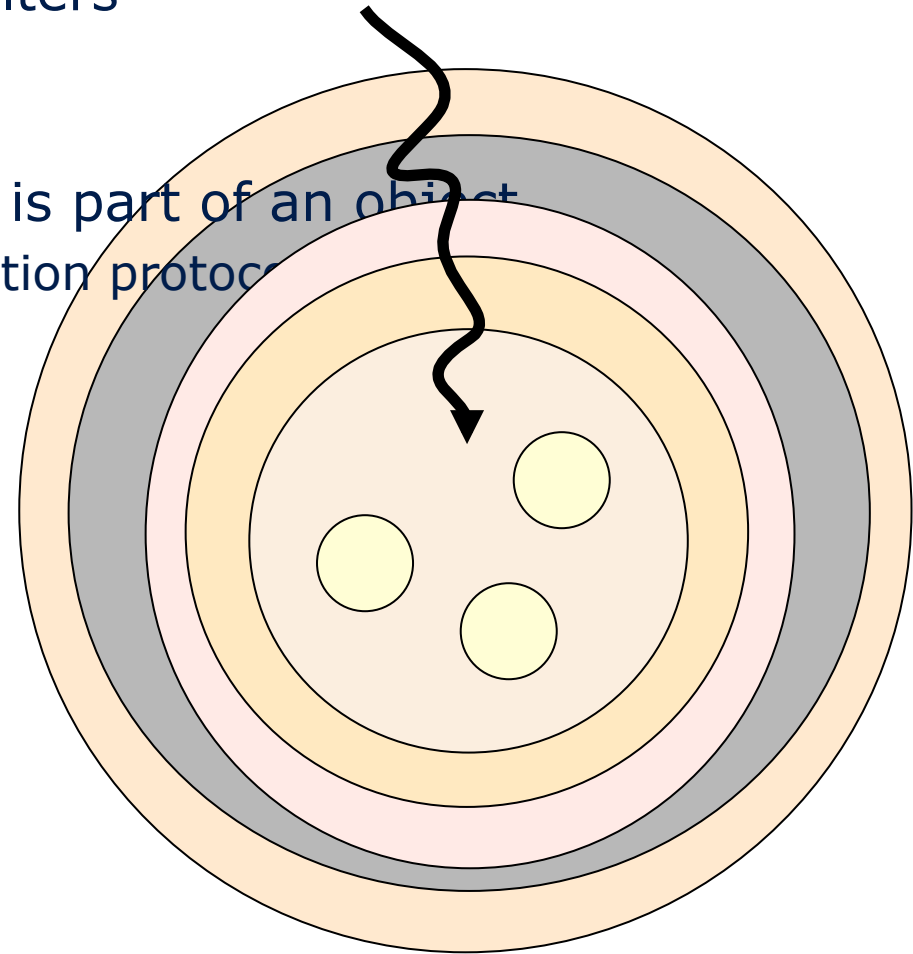
**Synchronization crosscut:** Because synchronization code *is reused* code, it is *crosscutting*

- Composition fixes crosscut between core and aspect





- Composition Filters (CF) wraps objects with *filters*
- Messages flow through the filters
  - are accepted or rejected
  - are modified
- A filter is an *interceptor* that is part of an object
  - superimposes a synchronization protocol

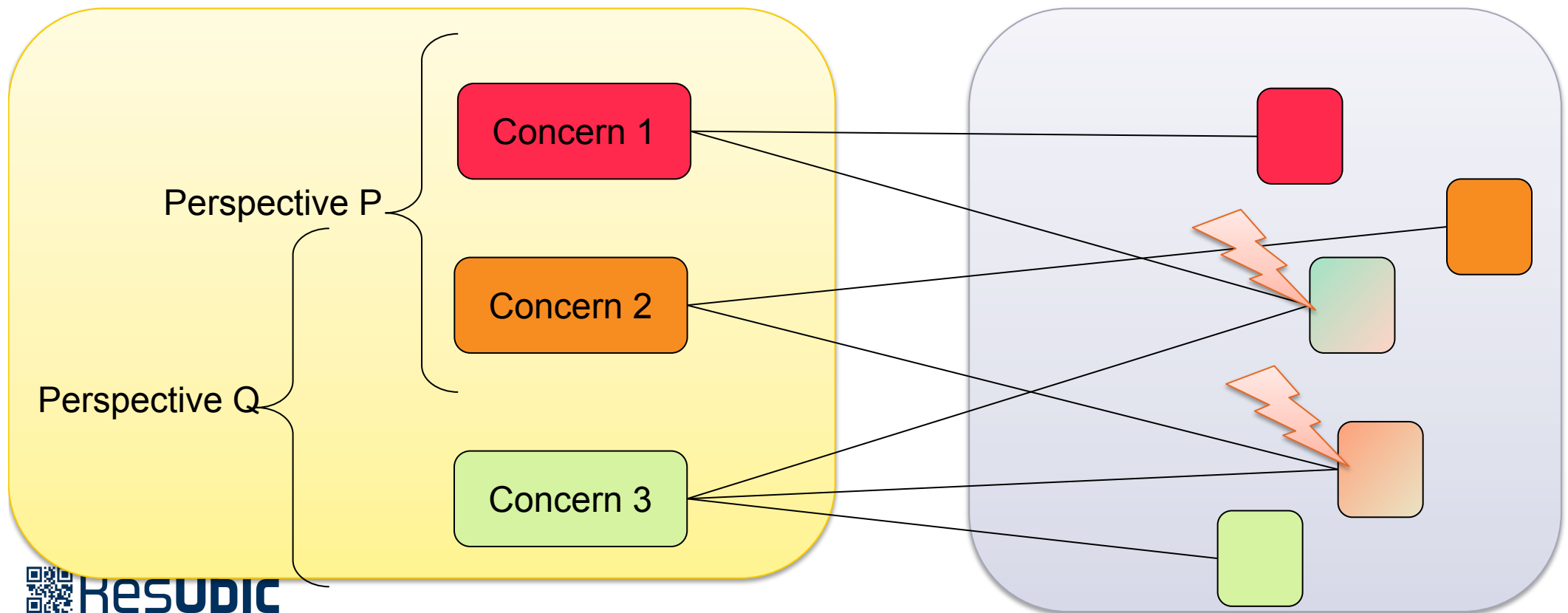


- Inheritance anomaly is solved by aspect composition over crosscut graphs
- But data dependencies are not covered
  - DOALL loops (without memory dependencies and alias-freedom) were the most successful form of parallelization because they map easily to MIMD

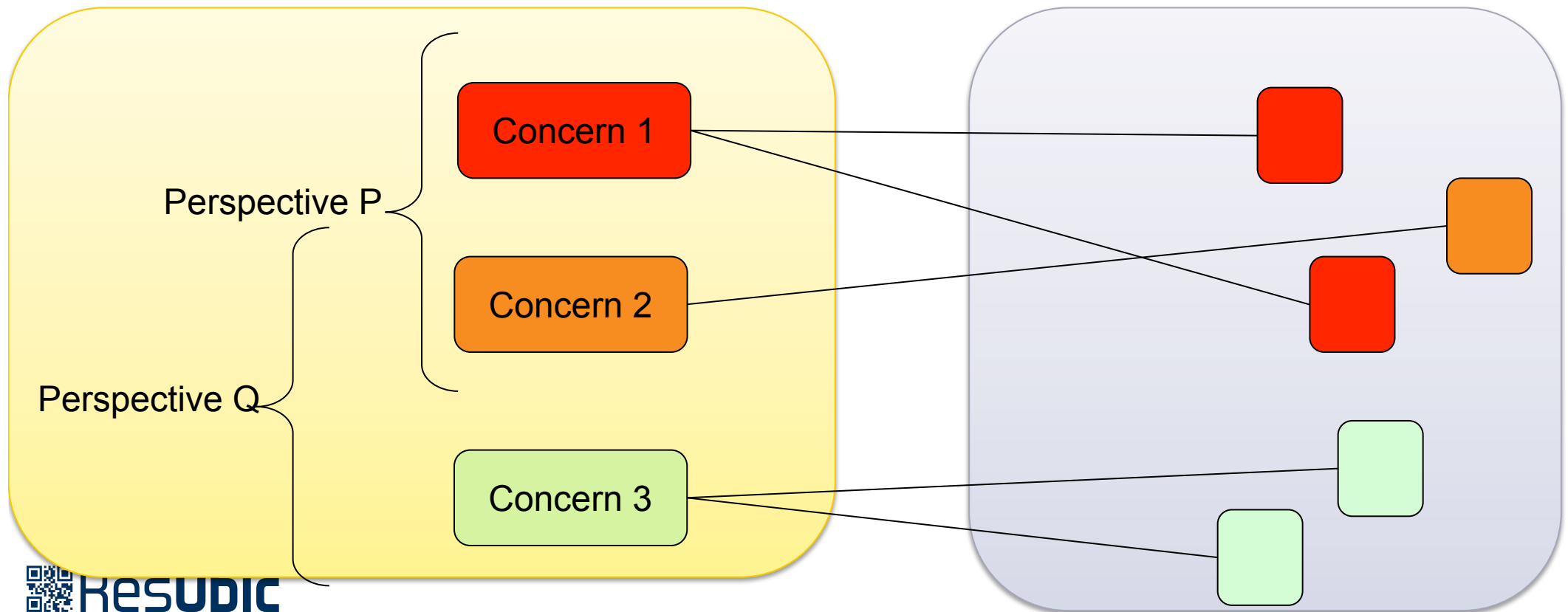
The relation of objects to memory is never modeled

- **Ch 2: How can software composition help to scale parallelism?**
- **Ch 2.1: For a scalable parallelism, how can we express alias absence with aspects and crosscutting?**
- **Ch 2.2: Hierarchical objects ensure alias disjointness to others. How to express this?**

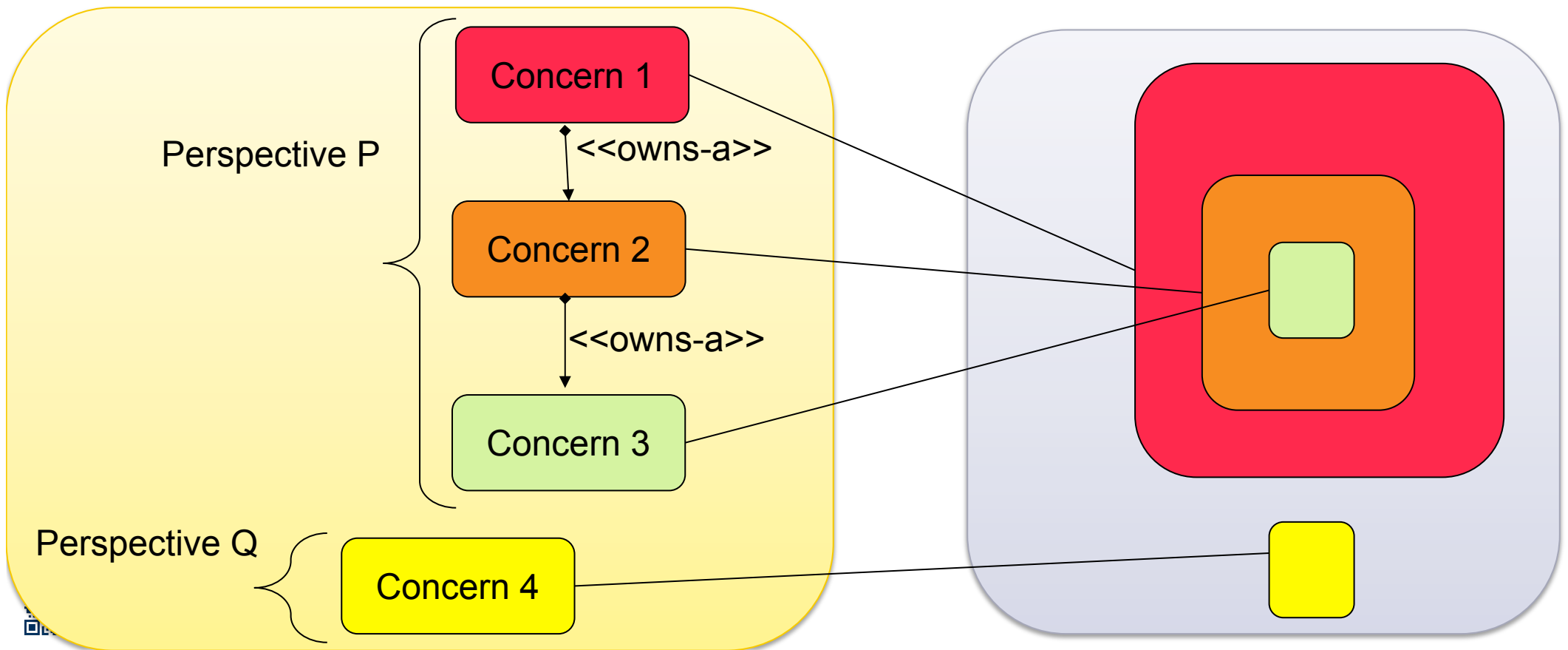
- Non-injectiveness of the concern mapping means aliases and dependencies (overlapping memory slices)



- Injective concern mapping yields alias absence and scalable slice-based parallelism
  - Already in HPF/95 patterns for non-overlapping (alias absense) were introduced for arrays as comment aspects



- Injective mappings of a owns-a concern hierarchy result in large objects without aliases for different perspectives
- (Business objects)



- **Ch 2.3: Which forms of alias-absence can be specified in SoC-Spaces with concern structure and concern mapping?**

- Whenever concern mappings are injective, parallelism scales

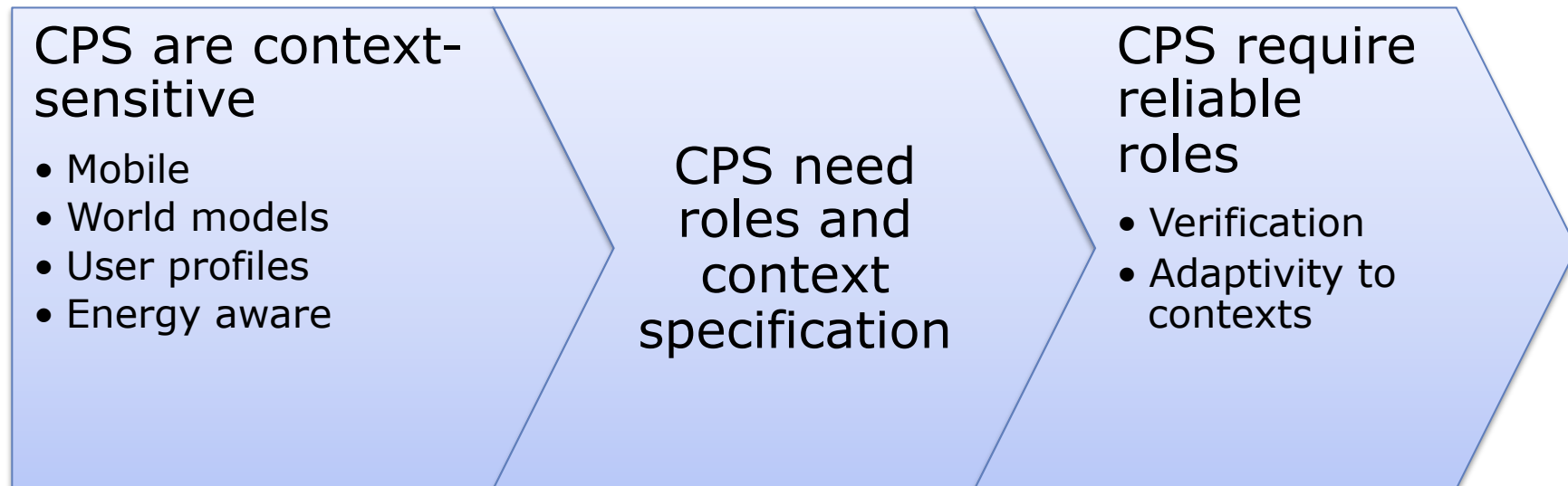


- SoC Pools belong to the composition level.
  - They should not be mixed with the algorithmic level.
  - They are independent of the algorithmic language and belong to the composition level
- Don't mix it like in classic parallel programming!

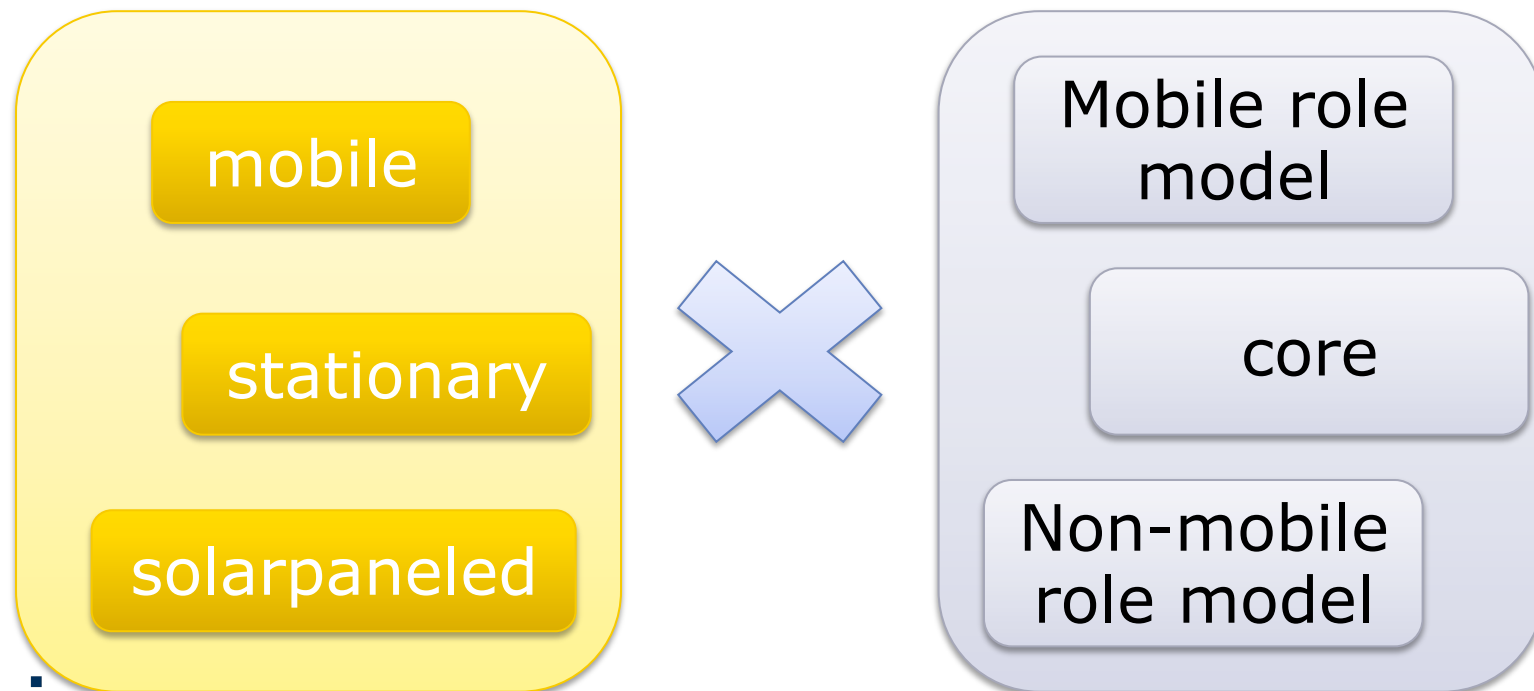
# 4. CHALLENGES FOR CONTEXT-SENSITIVITY

- Bachman's work (1987) on role models in databases allowed for context-sensitive querying, because roles model context.
- In database graphs, objects carry roles, so contextual querying is very important.

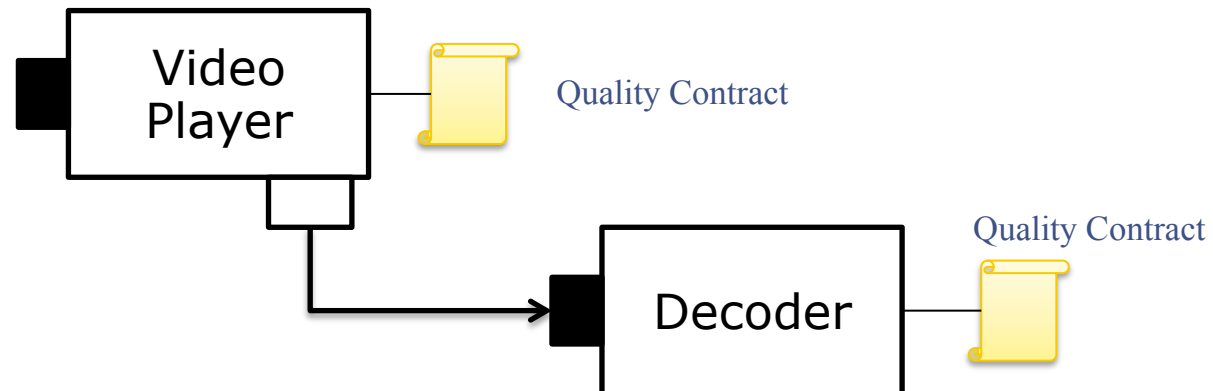
Because the standard data models did not provide roles, the query OO languages failed.



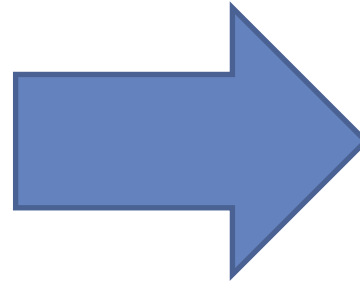
- [Context-aware programming of Hirschfeld et. al.]
- [Context-aware composition (Växjö, Linköping)]
- Roles belong to the artefact space
- Contexts to the concern space
- Switching on and off contexts adapts the application by enabling and disabling role models



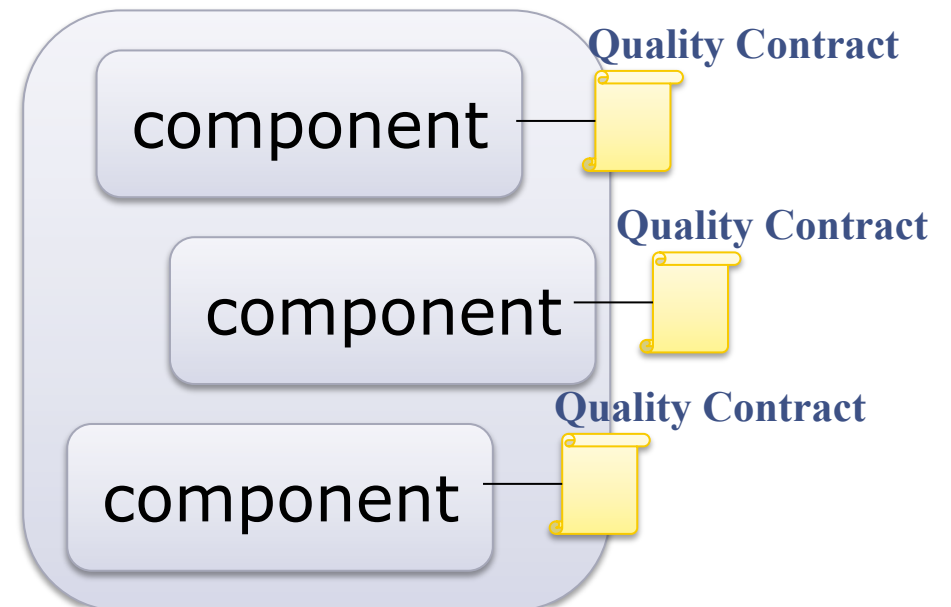
- **Quality contracts** are temporal-logic contracts by which the test coverage can be decided statically. They allow for writing statements over time that are verified
  - „in 5ms the system is in a safe state“
  - „the system is life and will never get stuck“
  - „After the door is closed, the train will eventually run“
  - „This robot cannot be functionally replaced – function of the swarm fails“
- Quality contracts assure modular verification of compositions



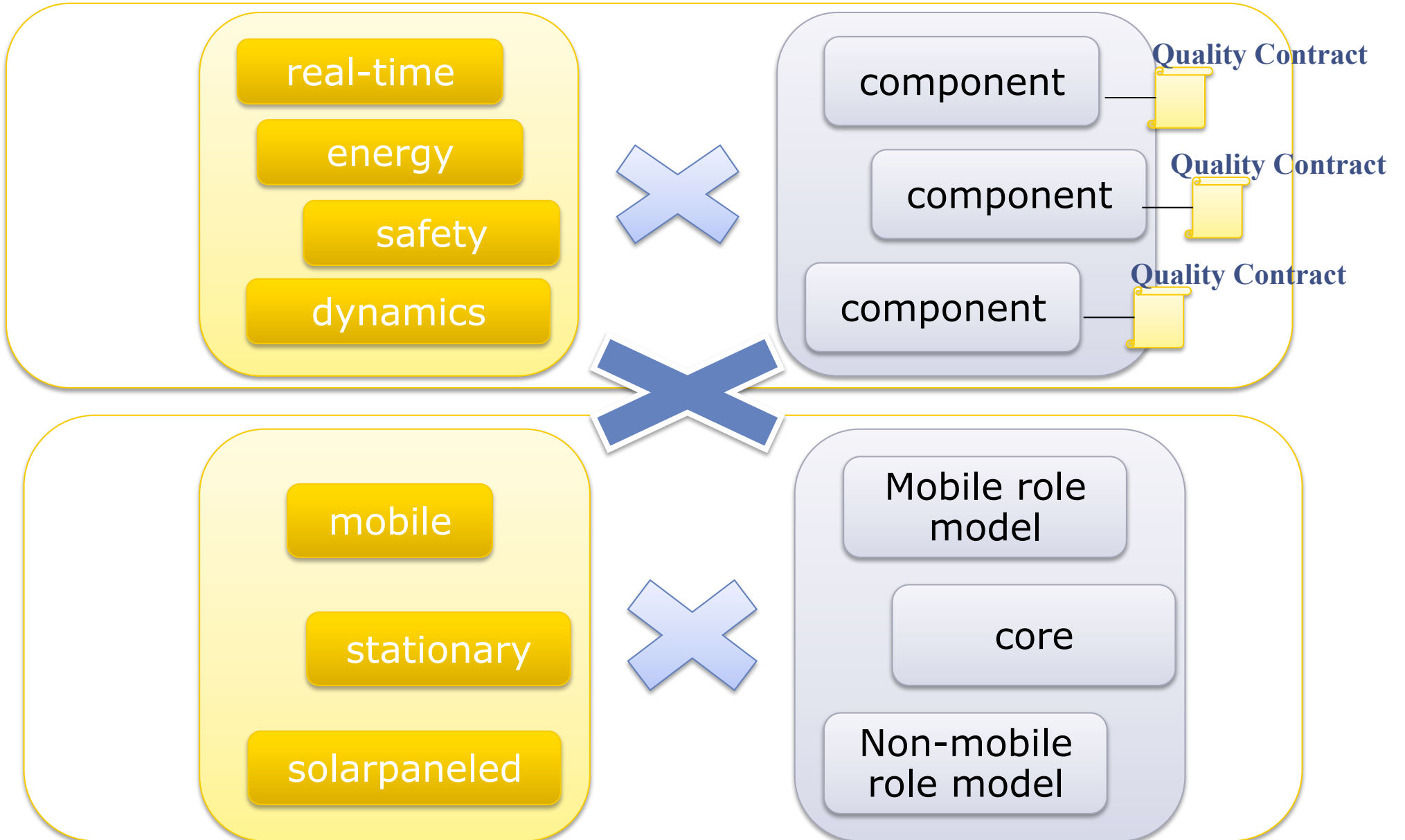
- CPS must be reliably composable
  - Functional Contracts
  - Quality Contracts
    - Real-time contracts
    - Energy contracts
    - Safety contracts
    - Spatial dynamics contracts



- Contract Checking of Quality Properties, e.g.
- Energy reserve for active fail-safety (AFS)
- „The robot swarm can still run 25s, so the shutdown to safe state has start in 5s“

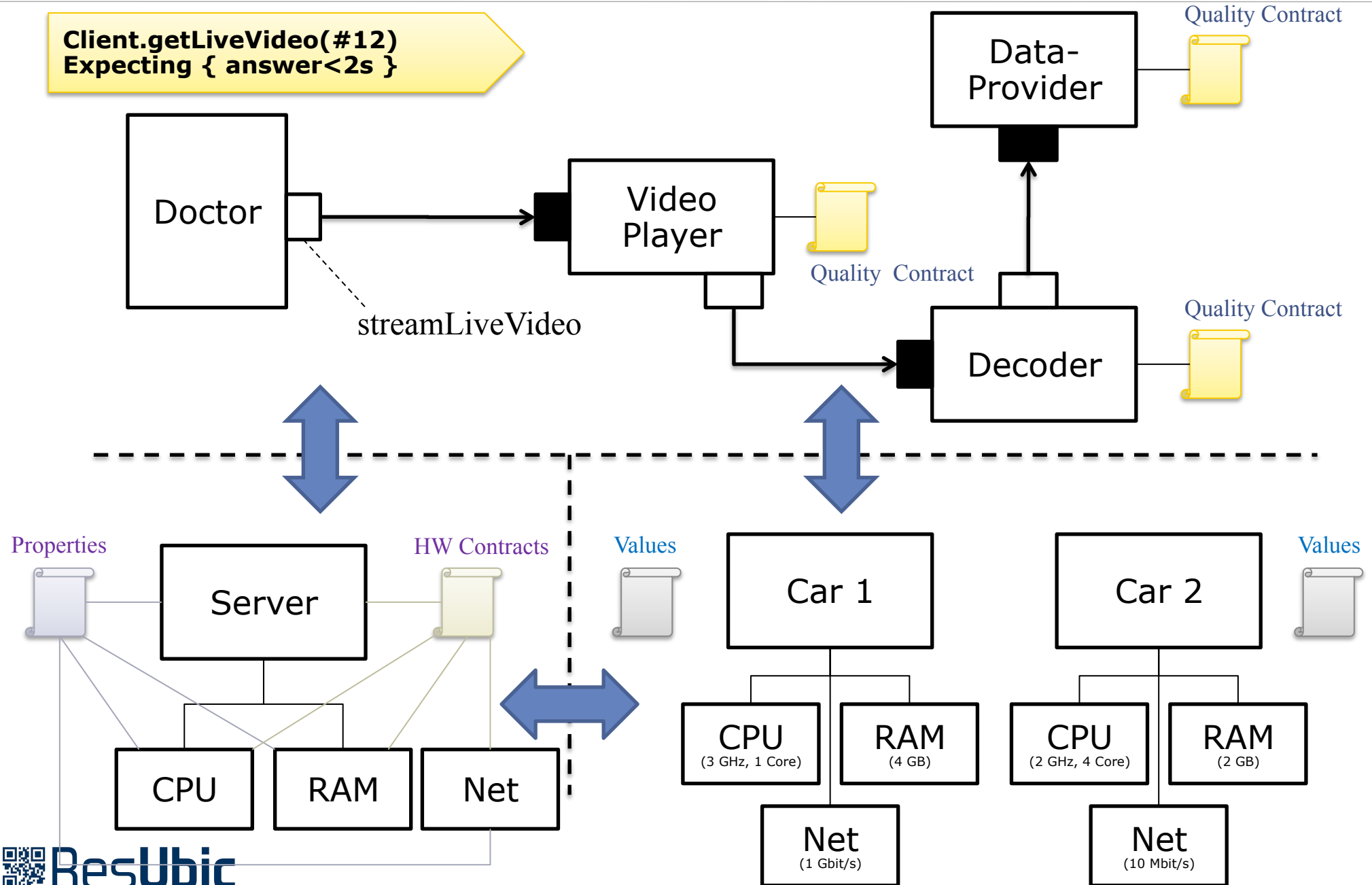




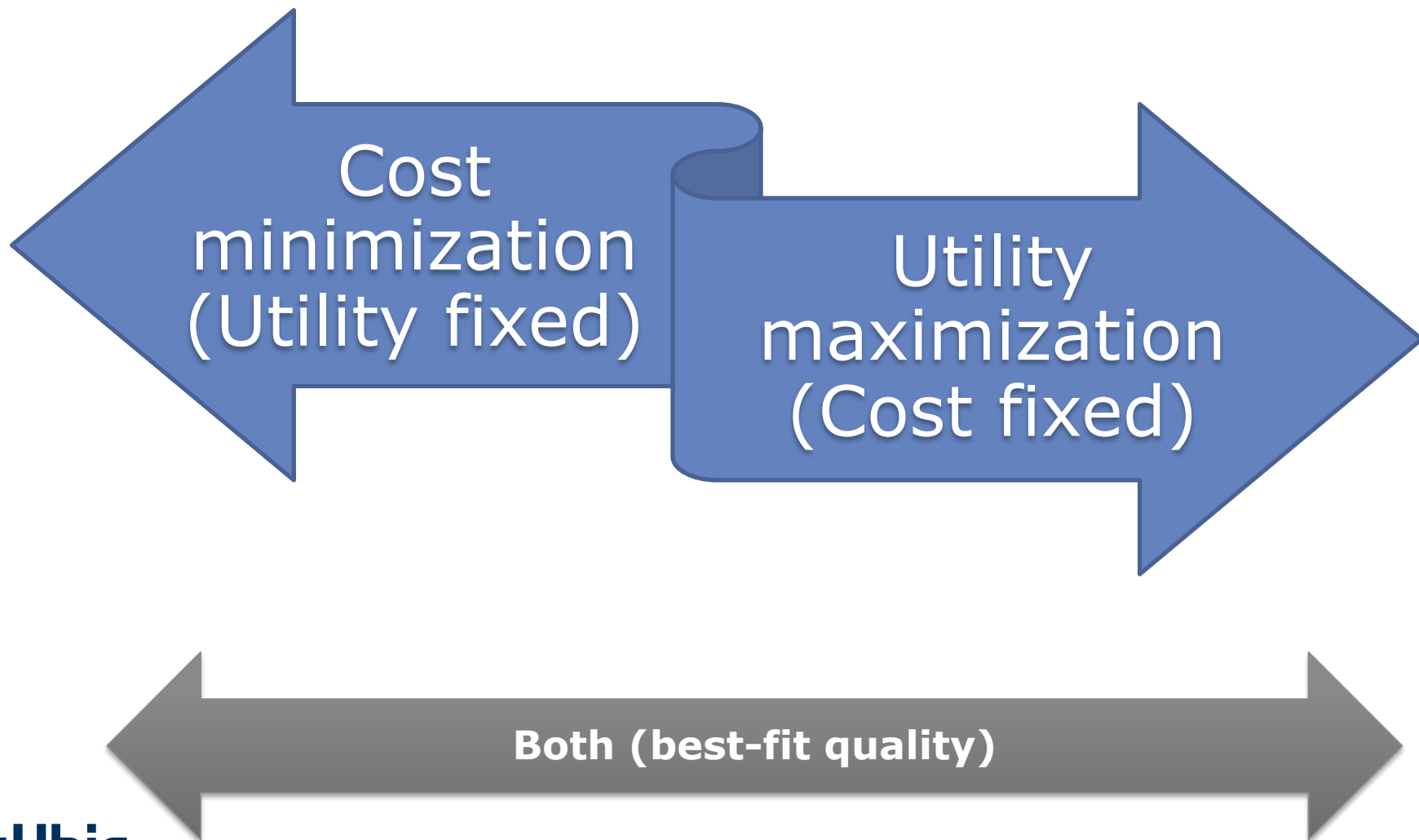


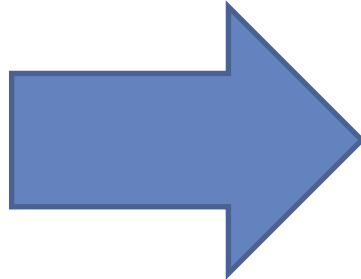
- **Ch 3: How can role models and contextual programming be combined with quality contracts?**
- **Ch 3.1 How can SoC spaces be applied systematically to reliable context-sensitivity?**

# 5. EFFICIENCY-BASED DEVELOPMENT WITH MULTI-OBJECTIVE OPTIMIZED ARCHITECTURES (MOO)

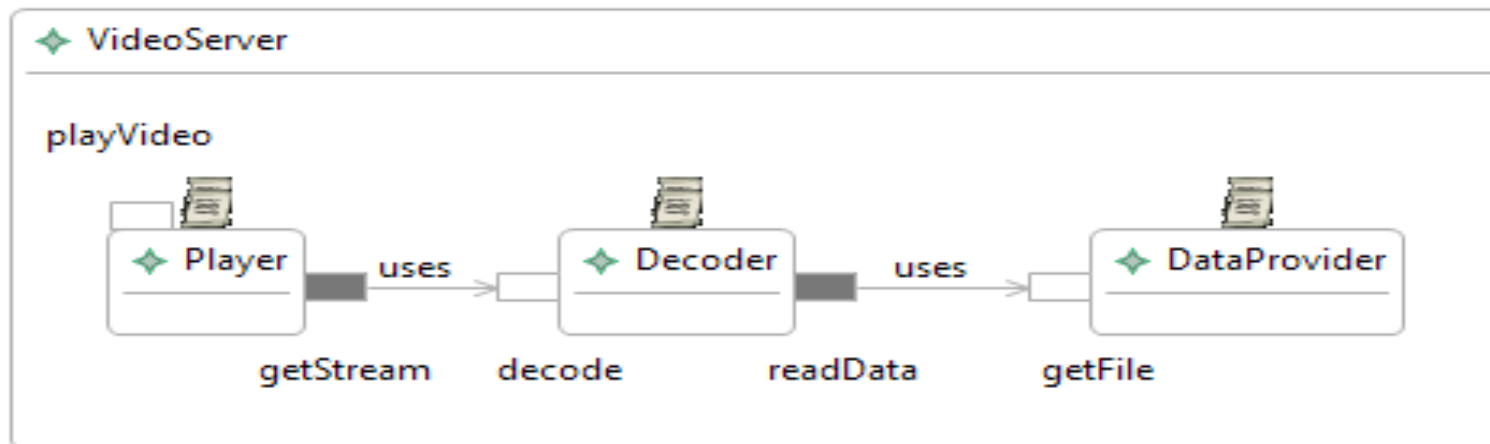


- Configuration is here a special form of composition
- All efficiency requirements can be handled



- CPS need adaptability
    - QoS adaptation
    - Context adaptation
  - Configuration Optimization
    - Determining Optimal Mappings of Software Components onto Hardware Resources
    - Resource minimization (energy)
    - Computation of pricing
- 
- **Ch 4: How can we reconfigure architectures with different cost and utility criteria (efficiency)?**
  - **Ch 4.1: Can we integrate energy consumption as resource?**
  - **Ch 4.2: Can we optimize with regard to multiple objectives?**

- Software is described using a CCM Structural Model
  - approx. SysML plus QCL contract language



- SW Components have provided/required ports (e.g. methods of classes)
- Quality-Modes and Implementations of SW Components are described using QCL contracts

```

VideoServer_Player.ecl
1 import ccm [../VideoServer.structure]
2 import ccm [../Server.structure]
3
4 contract VLC implements software Player {
5     mode highQuality {
6         requires component Decoder {
7             bitrate min: 5
8         }
9         requires resource CPU {frequency min: 1500}
10
11         provides framerate min: 20
12     }
13     mode lowQuality {
14         requires component Decoder {
15             bitrate min: 2
16         }
17         requires resource CPU {frequency
18
19         provides framerate min: 10
20     }
21 }

```

## Quality Modes

- SW Dependencies
- HW Dependencies
- Provided Properties

```

VideoServer_Player.ecl  VideoServer_DataProvider.ecl
1 import ccm [../VideoServer.structure]
2 import ccm [../Server.structure]
3
4 contract FileReader implements software DataProvider {
5     mode file {
6         provides throughput min: 20
7         requires resource HDD {
8             throughput min: 20
9         }
10    }
11 }
12
13 contract URLReader implements software DataProvider {
14     mode url {
15         provides throughput min: 5
16         requires resource Network {
17             bandwidth min: 5
18         }
19     }
20 }

```

*Where do the properties come from?*

*Where and how to define HW ?*



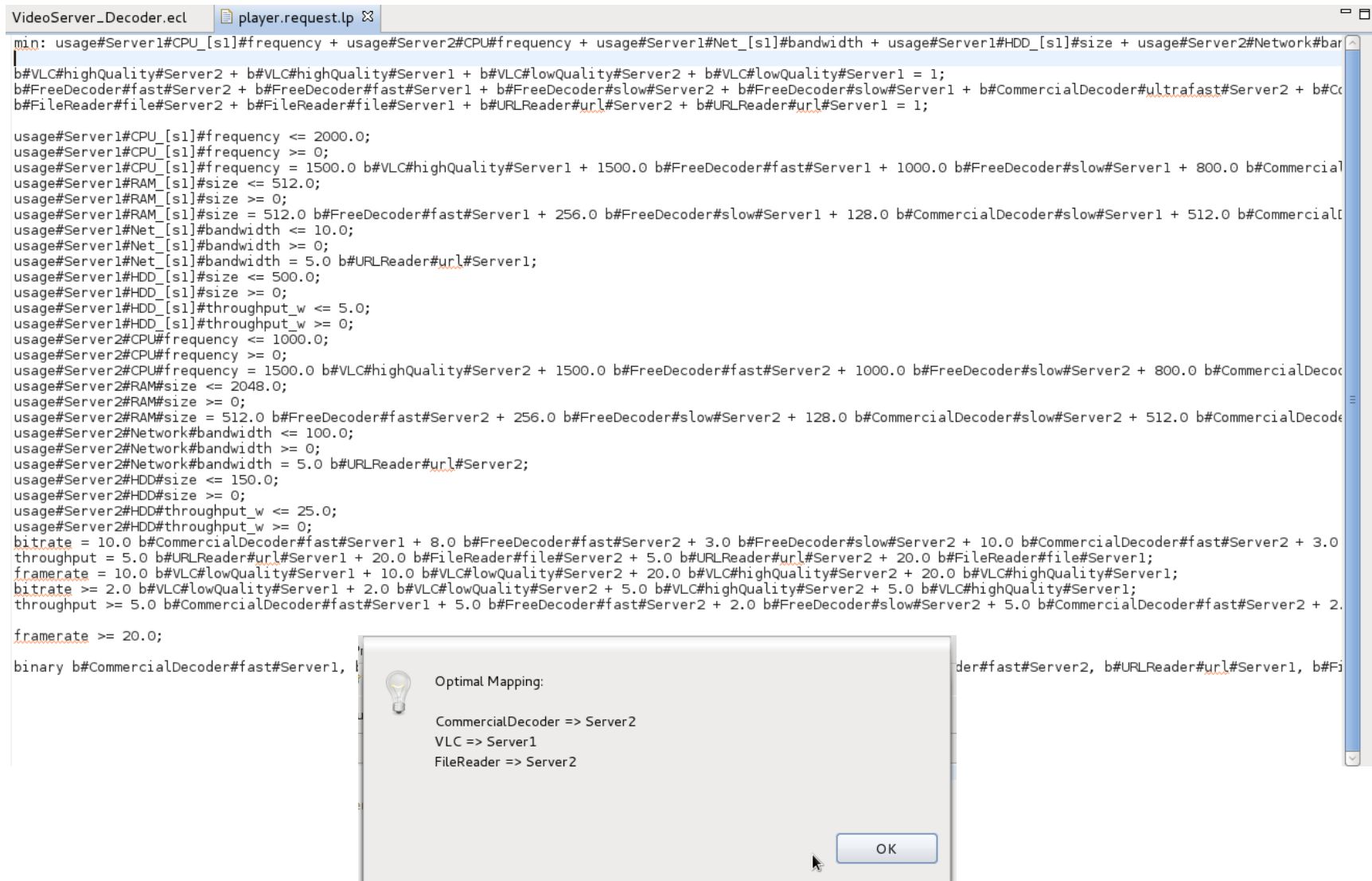
## Efficiency Challenge:

- Which implementations of the quality contracts
- in which quality mode
- on which resources
- give the most efficient configuration?

## Multi-Objective Optimization (MOO) with:

- Integer Linear Programming (exact)
- Pseudo-Boolean Optimization (exact)
- Ant Colony Optimization (approx.)
- Simulated Annealing (approx.)
- ...

- Solution of the ILP gives an optimal configuration



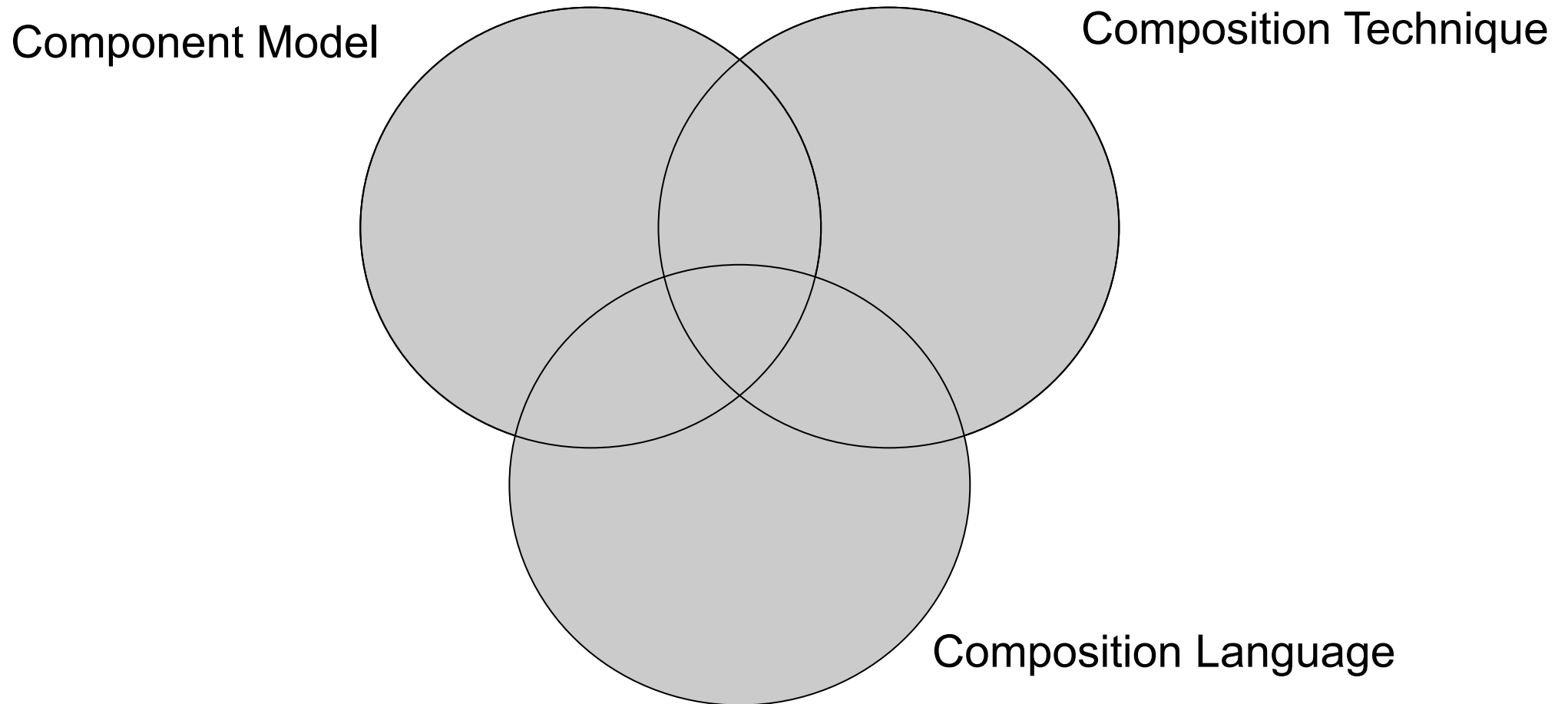
The screenshot shows a software window titled 'VideoServer\_Decoder.ecl' and 'player.request.lp'. The main area contains a list of constraints for an ILP solver, including CPU frequency, RAM size, network bandwidth, and HDD size for two servers, along with various usage and throughput constraints. An 'Optimal Mapping' dialog box is overlaid on the bottom right, displaying the following results:

```

Optimal Mapping:
CommercialDecoder => Server2
VLC => Server1
FileReader => Server2
  
```

An 'OK' button is visible at the bottom of the dialog box.

# 6. THE ULTIMATE CHALLENGE: SPECIFYING COMPOSITION SYSTEMS



All issues above do not belong to the component or algorithmic level, but to the composition level:

- SoC spaces
  - Hierarchical pools
  - SoC Pools
  - Context specifications
- Quality contracts
- Efficiency-based development with MOO

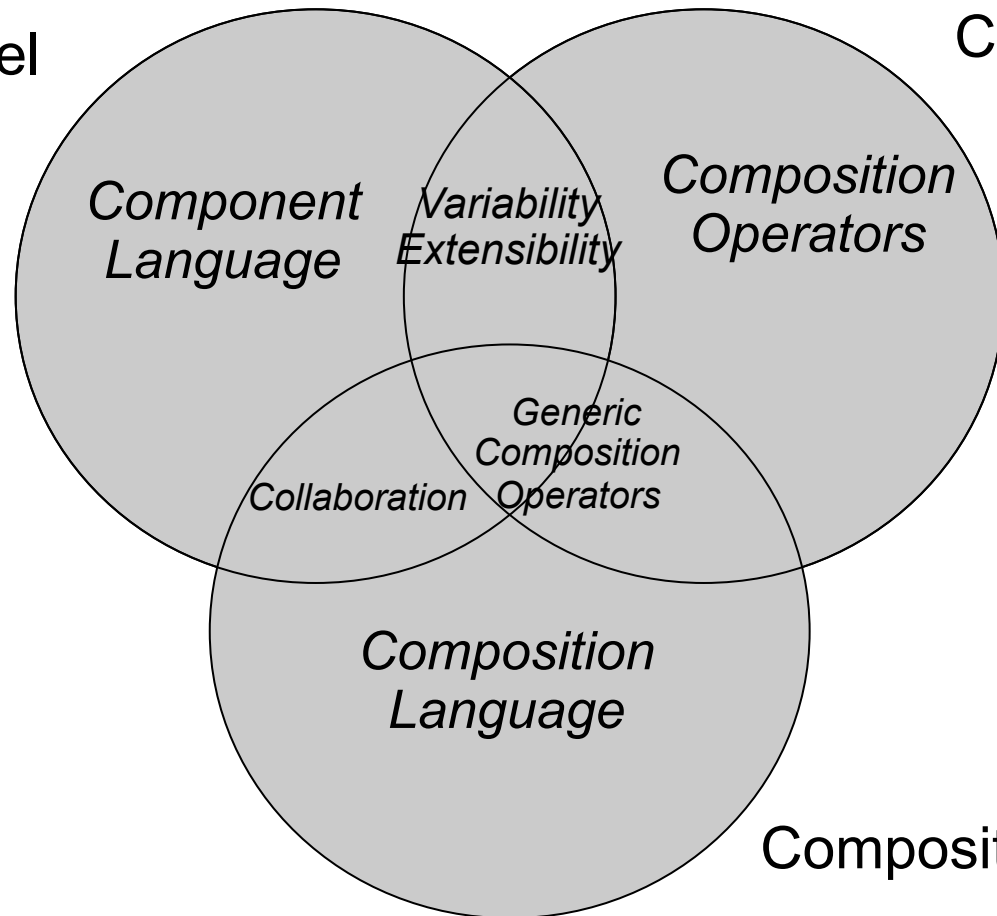
We want to reuse composition languages for **any** component language

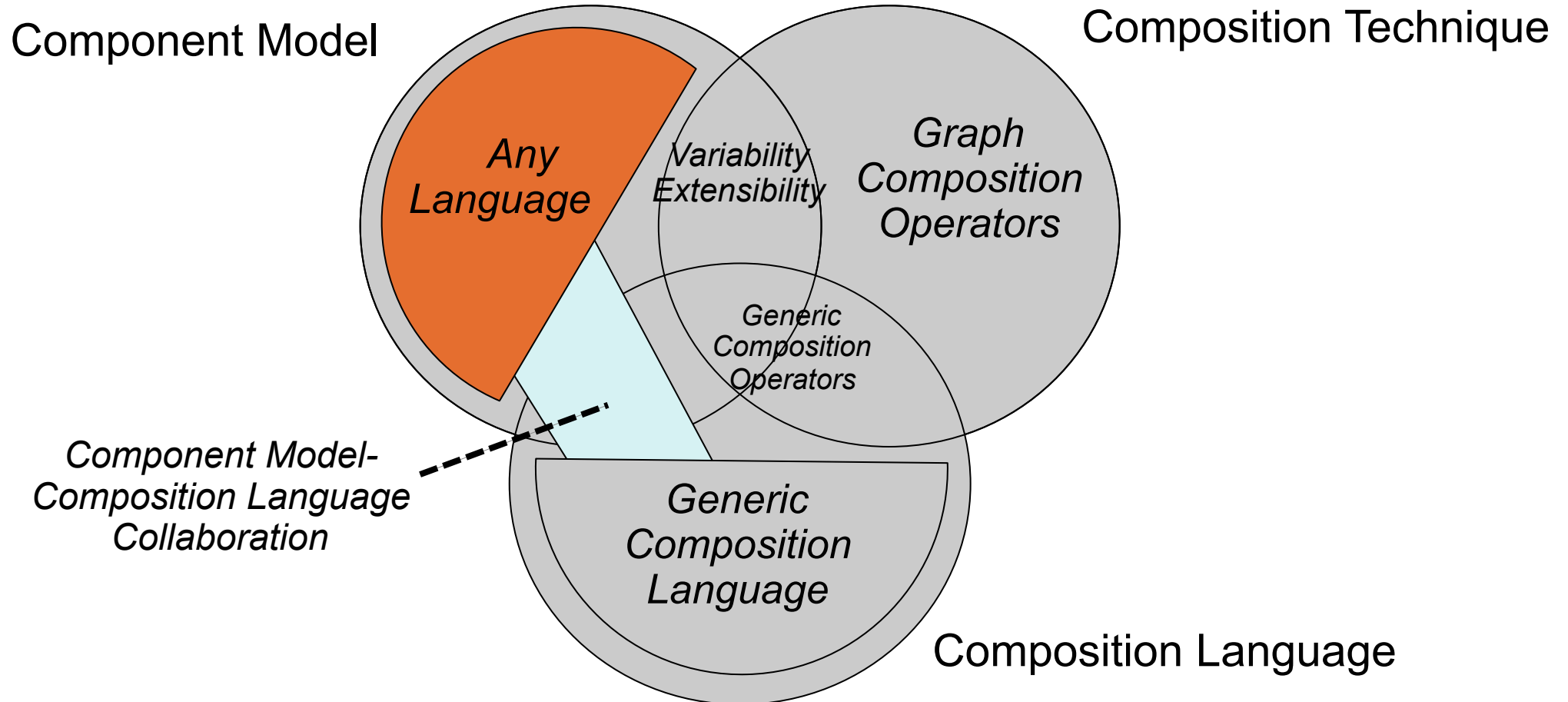
- Mixing composition level and component level has a lot of disadvantages:
  - Composition language cannot be reused for several algorithmic languages
  - Tools, editors, compilers, checkers, cannot be reused, but have to be constructed

Composition languages should be separate  
(Principle of separate composition)

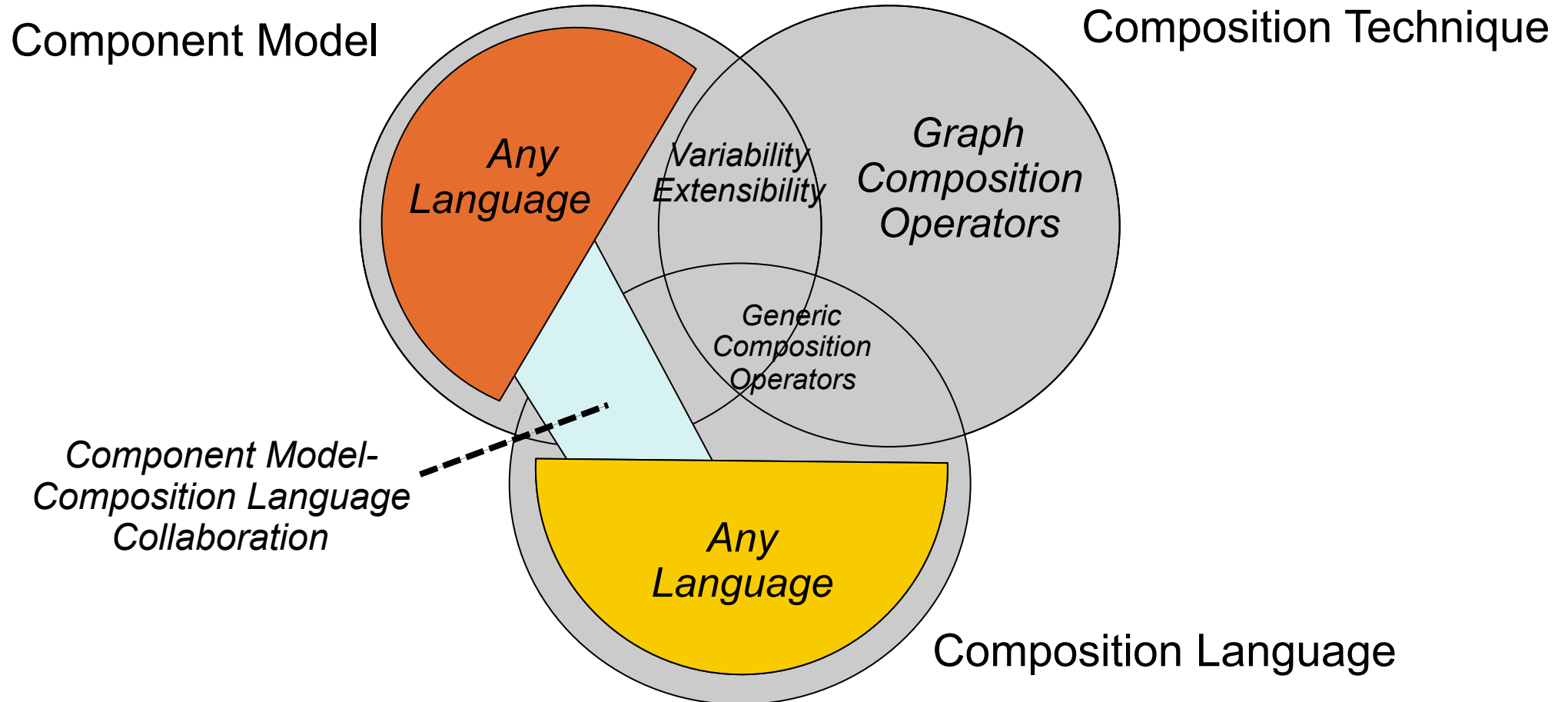
Component Model

Composition Technique

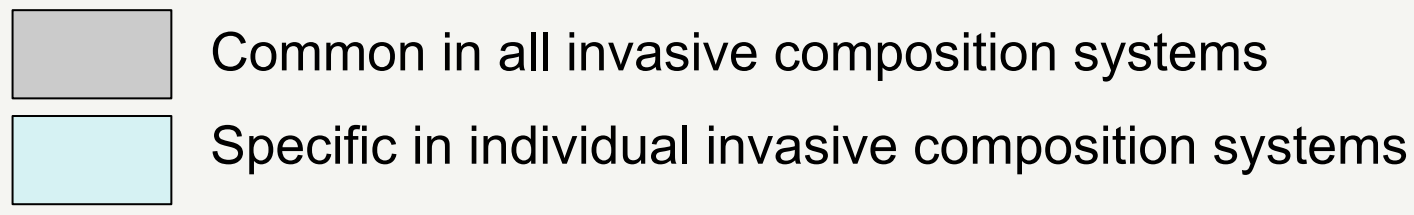
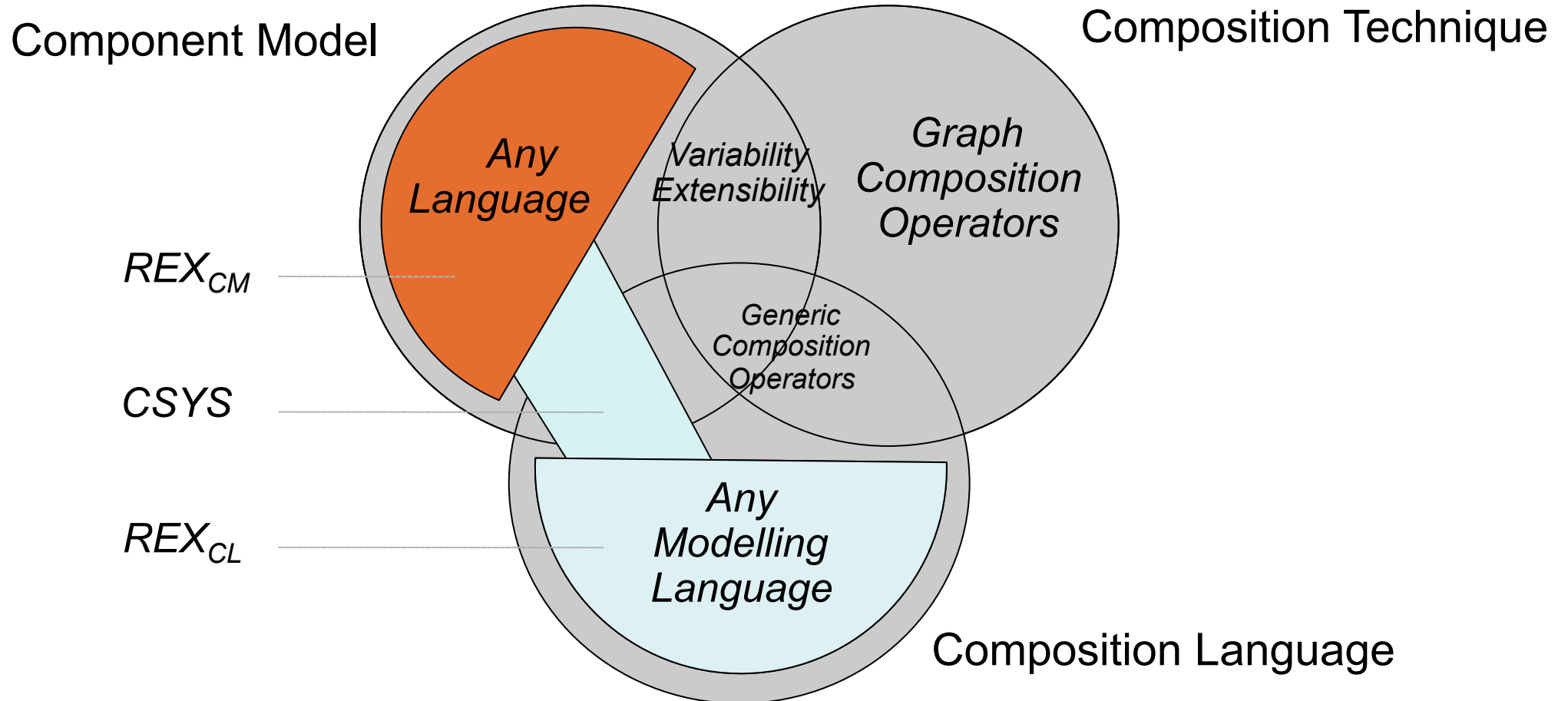








- **Ch 5: How do we specify composition systems?**
- **Ch 5.1: How can composition languages be separated from components (separate composition)?**
- **Ch 5.2: In-line compositions in components (write-easy) must be round-tripped with off-line, separate compositions (read-easy).**



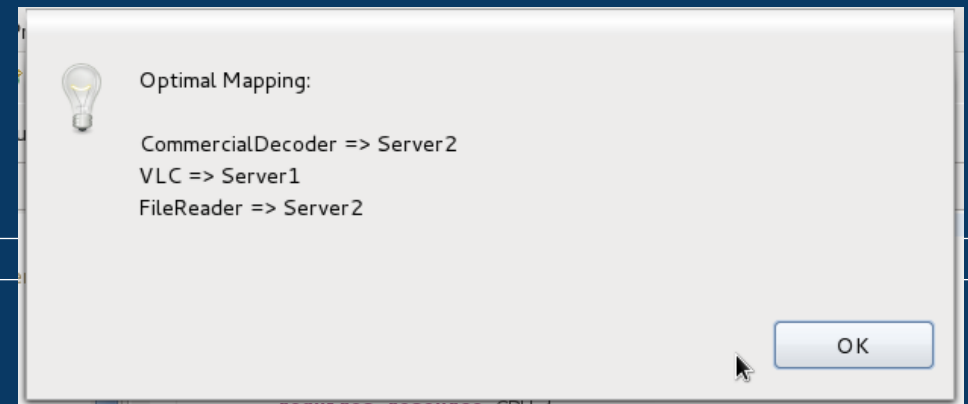
[Johannes 2010]

Life-by-Wire based on CPS will only be possible  
if software composition answers the following  
research questions:

- **Ch 1: How can we conceptualize separations of concerns so that decomposition and composition are supported?**
- **Ch 2: How can software composition help to scale parallelism?**
- **Ch 3: How can role models and contextual programming be combined with quality contracts?**
- **Ch 4: How can we reconfigure architectures with different cost and utility criteria (efficiency)?**
- **Ch 5: How do we specify composition systems?**

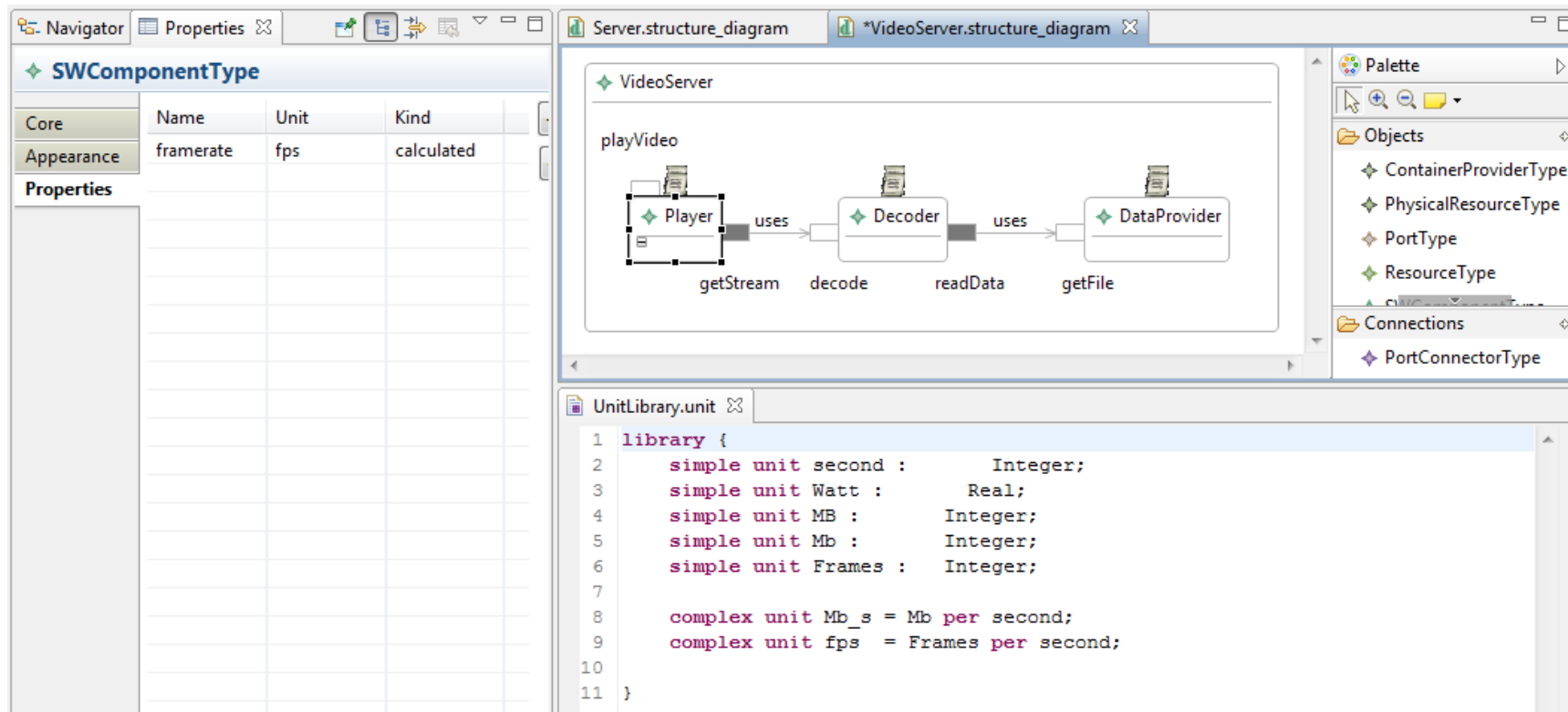
- Jendrik Johannes and Uwe Aßmann. Concern-based (de)composition of model-driven software development processes. In Dorina C. Petriu, Nicolas Rouquette, and Øystein Haugen, editors, MoDELS (2), volume 6395 of LNCS, pages 47-62. Springer, 2010.
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- Sebastian Götz, Claas Wilke, Sebastian Cech, and Uwe Aßmann. Sustainable Green Computing: Practices, Methodologies and Technologies, chapter Architecture and Mechanisms for Energy Auto Tuning. IGI Global, 2011.
- [Acatech] Agenda CPS. Acatech Studie März 2012.

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# Backup. The Software for Life-by-Wire: Multi-Objective Optimization Architectures (MOOA)

Prof. Uwe Aßmann  
Sebastian Götz



The screenshot displays a software development environment with three main panes:

- Left Pane (SWComponentType):** A table showing properties for a component type. The 'Appearance' section lists 'framerate' with unit 'fps' and kind 'calculated'.
- Middle Pane (Diagram):** A UML class diagram titled 'VideoServer' showing a 'playVideo' process. It involves three components: 'Player' (with 'getStream' operation), 'Decoder' (with 'decode' operation), and 'DataProvider' (with 'readData' and 'getFile' operations). Arrows labeled 'uses' connect Player to Decoder, and Decoder to DataProvider.
- Bottom Pane (UnitLibrary.unit):** A code editor showing the definition of a unit library with the following content:

```

1 library {
2   simple unit second :      Integer;
3   simple unit Watt :       Real;
4   simple unit MB :         Integer;
5   simple unit Mb :         Integer;
6   simple unit Frames :    Integer;
7
8   complex unit Mb_s = Mb per second;
9   complex unit fps = Frames per second;
10
11 }

```
- Right Pane (Palette):** A palette of component types including ContainerProviderType, PhysicalResourceType, PortType, ResourceType, and PortConnectorType.

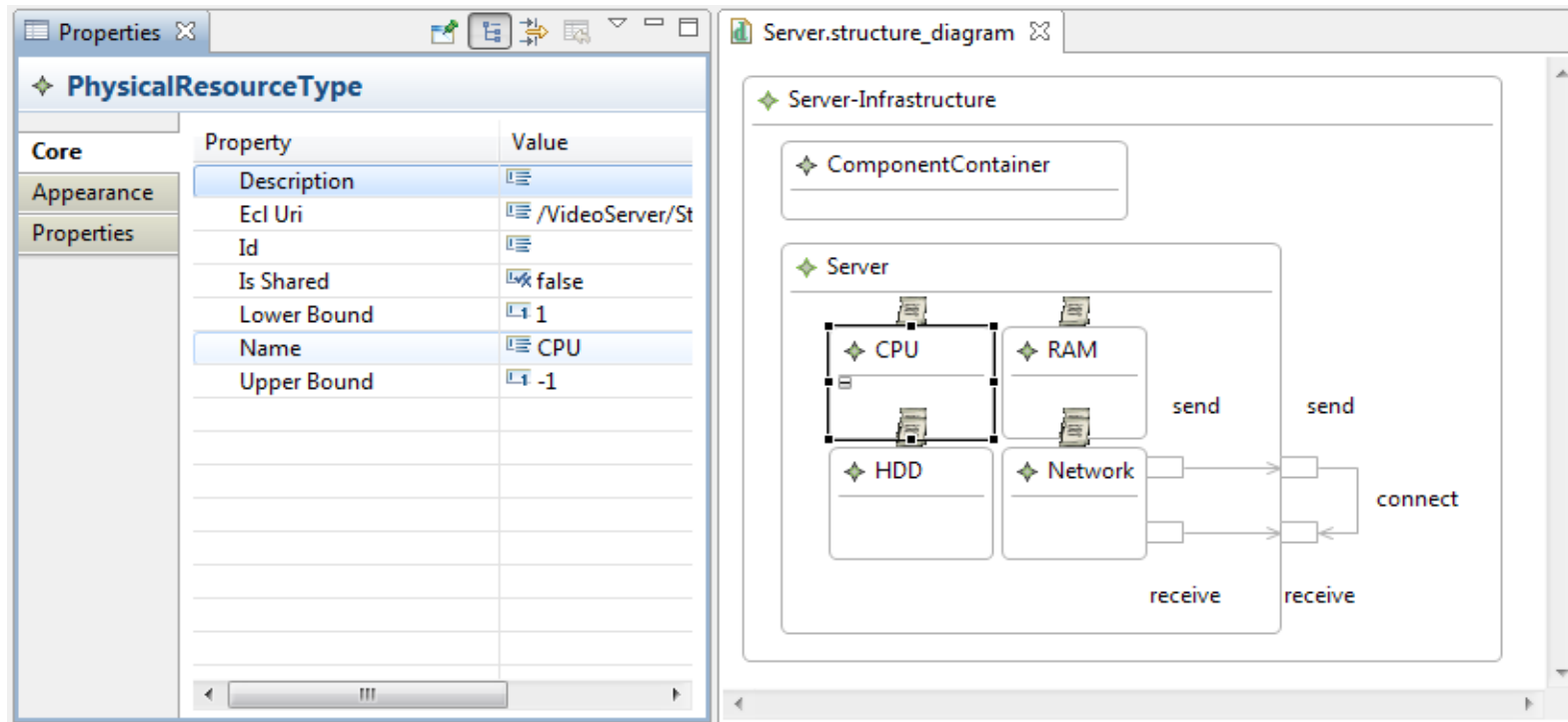
- Properties are defined for each ComponentType.
- Units can be defined
- They are either calculated, monitored or static.


**calculated:** free = total – used  
**monitored:** ResourceMgr.getX()  
**static:** fixed value for instance  
(e.g., size of HDD)



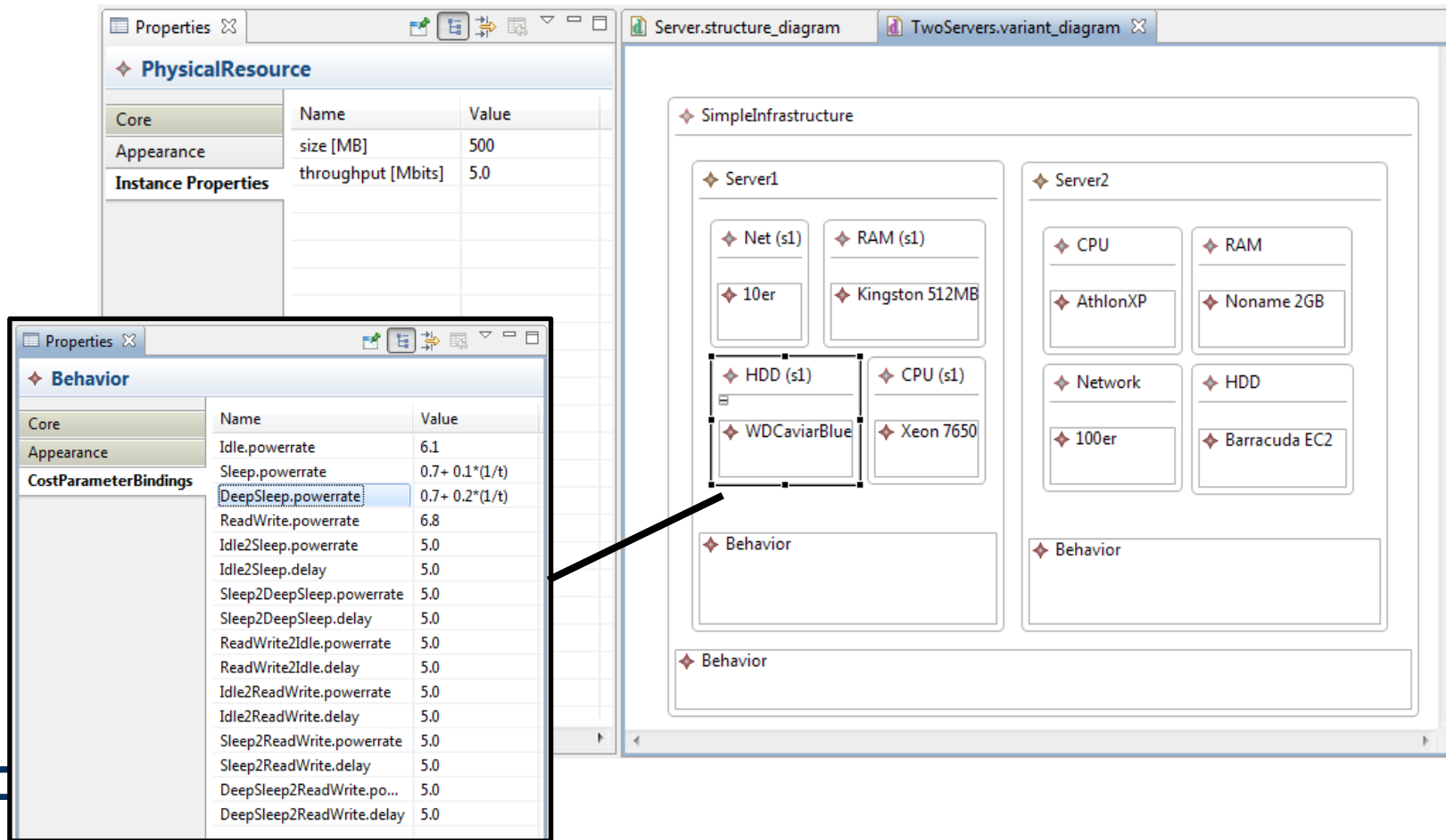
- Hardware Structural Model

- 
- Which ResourceTypes exist
- How they are connected
- Multiplicities - Contracts



- Hardware Variant Model  Concrete Resources (next Slide)
- Hardware Behavior using Energy State Charts

- concrete resources are modeled and connected to structural model
- values of static properties are assigned per resource
- behavior templates are assigned per resource,
- Cost parameters are assigned with values or formulas



The screenshot shows a software interface for modeling hardware variants. The main window displays a structural diagram of two servers, Server1 and Server2, with their components and associated behaviors. A properties window is open, showing the 'PhysicalResource' and 'Behavior' sections. A callout box highlights the 'Behavior' section of the properties window, showing a list of power rate and delay parameters with their values or formulas.

**PhysicalResource Properties:**

Core	Name	Value
Appearance	size [MB]	500
Instance Properties	throughput [Mbits]	5.0

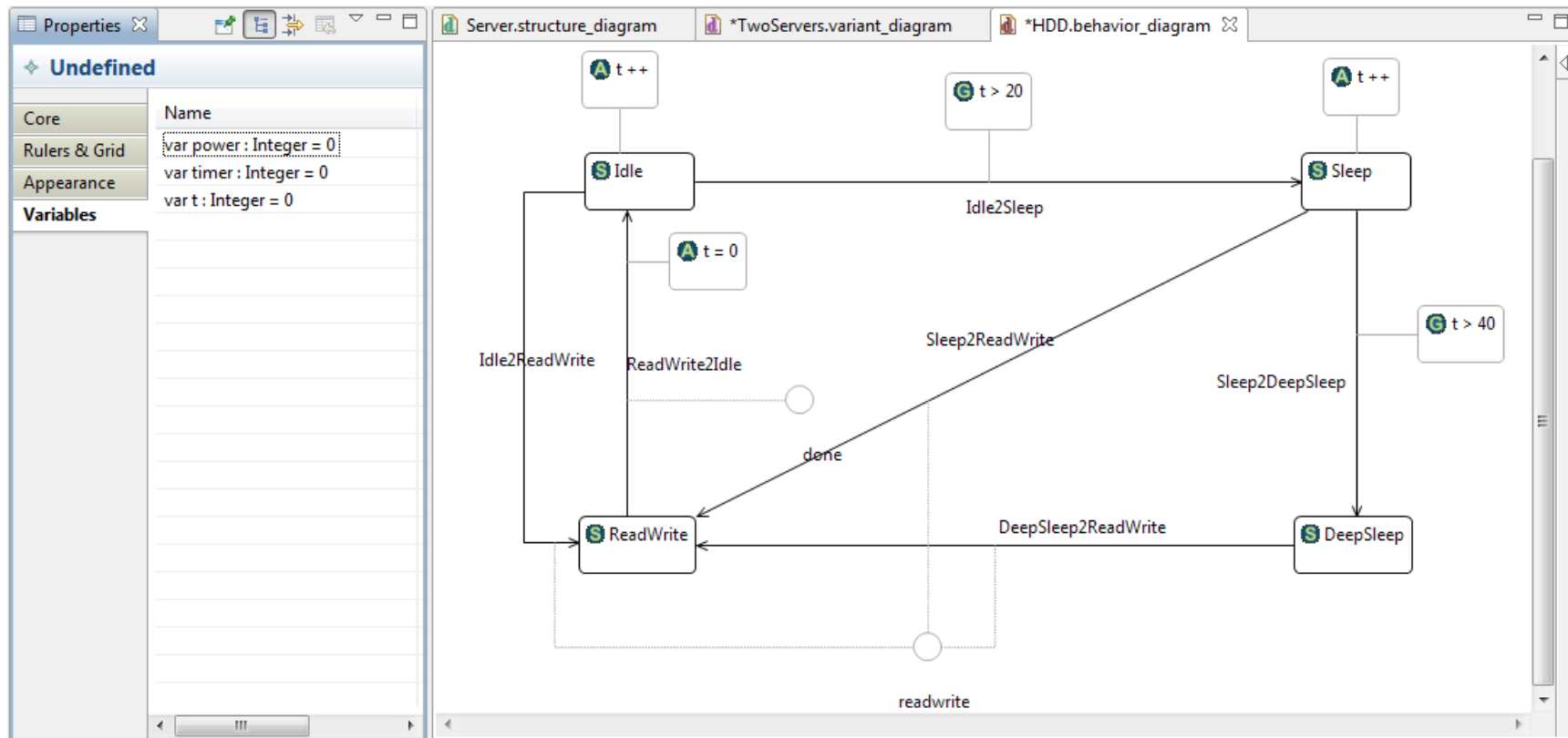
**Behavior Properties:**

Core	Name	Value
Appearance	Idle.powerrate	6.1
CostParameterBindings	Sleep.powerrate	$0.7 + 0.1 * (1/t)$
	DeepSleep.powerrate	$0.7 + 0.2 * (1/t)$
	ReadWrite.powerrate	6.8
	Idle2Sleep.powerrate	5.0
	Idle2Sleep.delay	5.0
	Sleep2DeepSleep.powerrate	5.0
	Sleep2DeepSleep.delay	5.0
	ReadWrite2Idle.powerrate	5.0
	ReadWrite2Idle.delay	5.0
	Idle2ReadWrite.powerrate	5.0
	Idle2ReadWrite.delay	5.0
	Sleep2ReadWrite.powerrate	5.0
	Sleep2ReadWrite.delay	5.0
	DeepSleep2ReadWrite.po...	5.0
	DeepSleep2ReadWrite.delay	5.0

**Structural Diagram Components:**

- Server1: Net (s1) 10er, RAM (s1) Kingston 512MB, HDD (s1) WDCavariBlue, CPU (s1) Xeon 7650, Behavior
- Server2: CPU AthlonXP, RAM Noname 2GB, Network 100er, HDD Barracuda EC2, Behavior





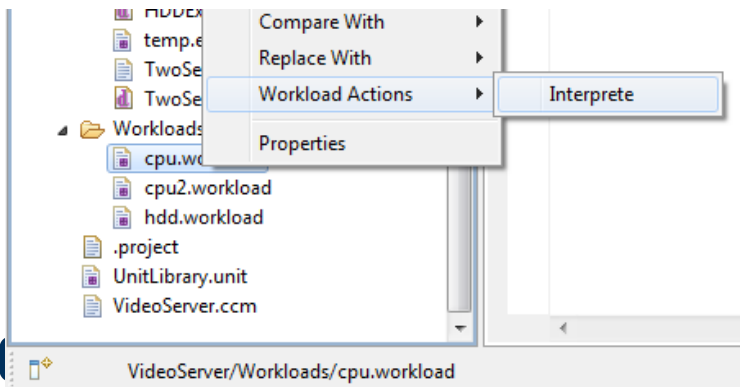
- use cost parameters instead of concrete values
  - reuse for resources of same kind
- can be executed using workload descriptions

```

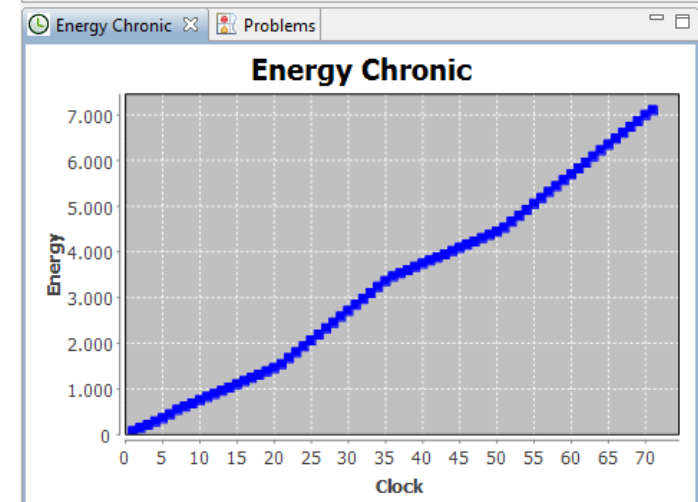
1 import ccm [./VideoServer/Variants/HDDExampleTest.variant]
2
3 Workload TestHDD for WDHDD {
4   readwrite at 2
5   done at 5
6   readwrite at 20
7   done at 30
8   readwrite at 60
9   done at 100
10  readwrite at 150
11  done at 155
12 }
  
```

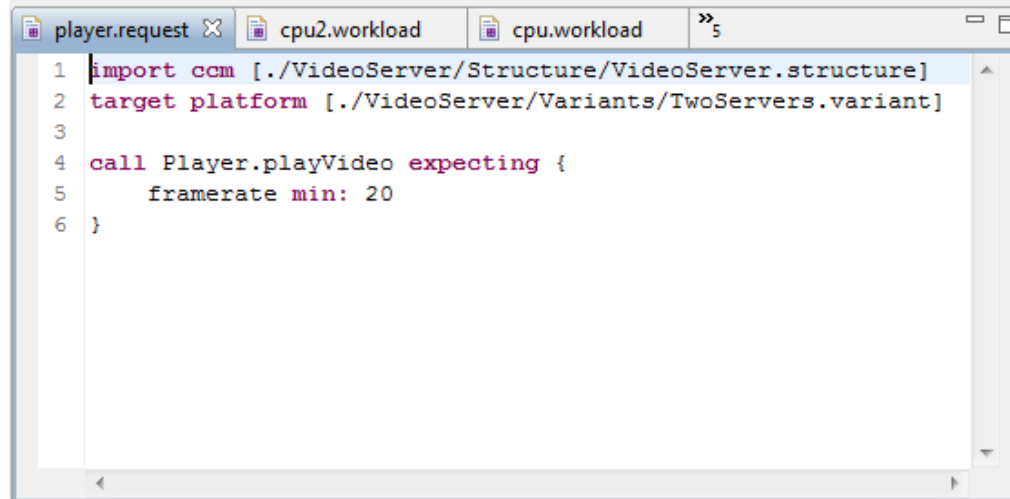
```

1 import ccm [./VideoServer/Variants/CPUEXampleTest.variant]
2
3 Workload someName for Xeon {
4   work at 5
5   work at 20 for 15
6   work at 50 for 20
7 }
  
```



Clock	Power	State	Config
1	70	Idle	t = 1, x =
2	140	Idle	t = 2, x =
3	210	Idle	t = 3, x =
4	280	Idle	t = 4, x =
5	350	Idle	t = 5, x =
6	440	Busy	t = 5, x = 1
7	540	Idle	t = 1, x = 1
8	610	Idle	t = 2, x = 1
9	680	Idle	t = 3, x = 1
10	750	Idle	t = 4, x = 1
11	820	Idle	t = 5, x = 1
12	890	Idle	t = 6, x = 1
13	960	Idle	t = 7, x = 1
14	1030	Idle	t = 8, x = 1
15	1100	Idle	t = 9, x = 1
16	1170	Idle	t = 10, x = 1
17	1240	Idle	t = 11, x = 1
18	1310	Idle	t = 12, x = 1
19	1380	Idle	t = 13, x = 1
20	1450	Idle	t = 14, x = 1
21	1540	Busy	t = 14, x = 2
22	1670	Busy	t = 14, x = 3
23	1800	Busy	t = 14, x = 4
24	1930	Busy	t = 14, x = 5
25	2060	Busy	t = 14, x = 6
26	2190	Busy	t = 14, x = 7
27	2320	Busy	t = 14, x = 8
28	2450	Busy	t = 14, x = 9
29	2580	Busy	t = 14, x = 10
30	2710	Busy	t = 14, x = 11
31	2840	Busy	t = 14, x = 12





```
1 import ccm [./VideoServer/Structure/VideoServer.structure]
2 target platform [./VideoServer/Variants/TwoServers.variant]
3
4 call Player.playVideo expecting {
5     framerate min: 20
6 }
```

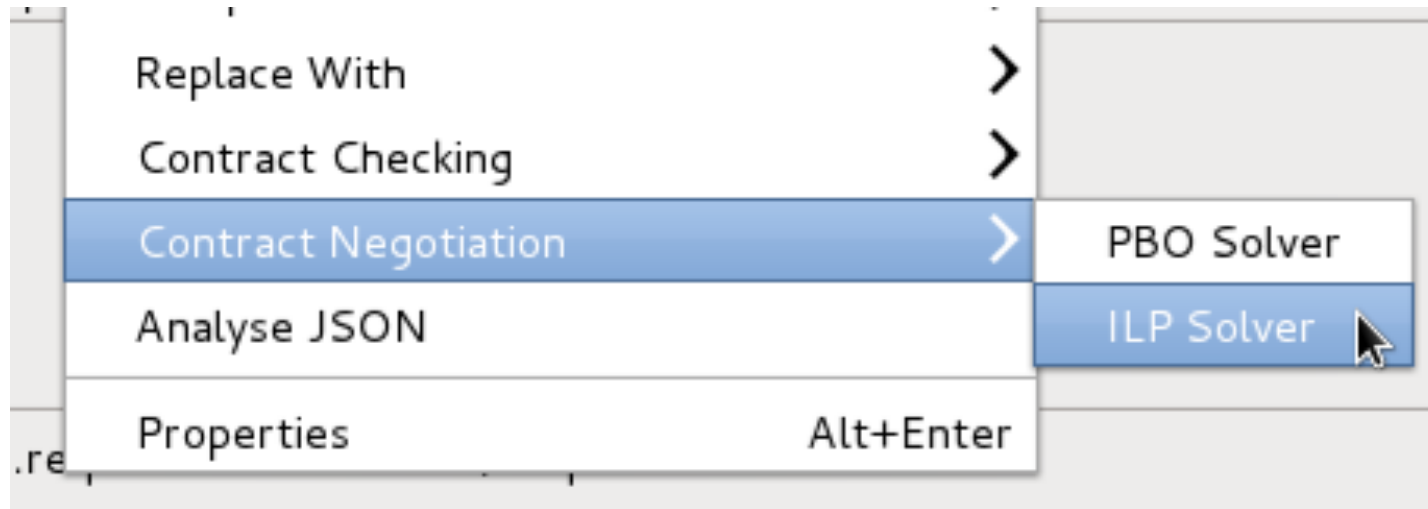
- Users call methods on SW Components
- They state their (quality) expectations explicitly
- HW infrastructure is selected
  
- Then the software configuration is automatically optimized with Multi-Objective-Optimization (MOO)

## Question:

- Which implementations of the contracts
- in which quality mode
- on which resources
- give the most efficient configuration?

## Multi-Objective Optimization (MOO) with:

- Integer Linear Programming (exact)
- Pseudo-Boolean Optimization (exact)
- Ant Colony Optimization (approx.)
- Simulated Annealing (approx.)
- ...



- An ILP is generated for a certain request on a software component and a hardware variant.